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Measurement and characterisation of radiated underwater sound from a 3.6 MW monopile wind turbine

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This paper describes underwater sound pressure measurements obtained in close proximity (~ 50 m) to two individual wind turbines, over a 21-day period, capturing the full range of turbine operating conditions. The sound radiated into the water was characterised by a number of tonal components, which are thought to primarily originate from the gearbox for the bandwidth measured. The main signal associated with the turbine operation had a mean-square sound pressure spectral density level which peaked at 126 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ at 162 Hz. Other tonal components were also present, notably at frequencies between about 20 and 330 Hz, albeit at lower amplitudes. The measured sound characteristics, both in terms of frequency and amplitude, were shown to vary with wind speed. The sound pressure level increased with wind speed up to an average value of 128 dB re $1 \mu\text{Pa}$ at a wind speed of about 10 ms^{-1} , and then showed a general decrease. Overall, differences in the mean-square sound pressure spectral density level of over 20 dB were observed across the operational envelope of the turbine. [<http://dx.doi.org/10.1121/1.4964824>]

[APL]

Pages: 2913–2922

I. INTRODUCTION

At the end of 2015, the United Kingdom had over 1450 operational offshore wind turbines, with nearly 2000 further offshore wind turbines either under construction or consented (RenewableUK, 2015). The trend is mirrored globally, with the number of wind turbines expected to increase (Global Wind Council, 2015). This has the potential to radiate underwater noise into the marine environment, with concerns over the potential impacts of underwater noise on the marine environment reflected within legislation; the Marine Strategy Framework Directive (European Parliament and Council, 2008) considers underwater noise a pollutant; the EU Habitats Directive (European Council, 1992) and the US Marine Mammal Protection Act (MMPA) connect underwater noise with wildlife legislation.

The first offshore wind turbine was installed in 1990 in Sweden (Bilgili *et al.*, 2011). Since then, several accounts of underwater sound associated with an operational wind turbine have been published in research reports (Westerberg, 1994; Degn, 2000; Lindell, 2003; Nedwell *et al.*, 2004; Thomsen *et al.*, 2006; Nedwell *et al.*, 2007; Nedwell *et al.*, 2011a,b), a number of which are reviews or compilations of the same datasets for the purposes of assessing the noise impact on marine life. Madsen *et al.* (2006) completed a review of some of the available data concluding that the resulting underwater noise is unlikely to impair hearing in marine mammals. Wahlberg and Westerberg (2005) also

used some of these previously measured data to assess the potential impact on fish around operational wind turbines. Further accounts of underwater noise measurements from operational wind turbines have also been reported in conference proceedings (Betke *et al.*, 2004; Cheesman, 2016; Norro *et al.*, 2015). Koschinski *et al.* (2003) and Tougaard *et al.* (2009) published underwater sound pressure measurements of offshore wind turbines in the peer-reviewed literature primarily with acoustic data presented in one-third octave bands to assess the potential for impact on seals and harbour porpoise. Koschinski *et al.* (2003) measured simulated 2 MW wind turbine noise, while Tougaard *et al.* (2009) measured the sound radiated from offshore wind turbines with rated capacity between 0.45 MW to 2 MW. Overall, the available data include measurements for wind turbines with rated capacity between 0.22 to 5 MW, and with gravity, tripod and monopile foundations, in water depths between about 6 and 20 m. The study reported here is of a Siemens 3.6 MW SWT-3.6-107 turbine, one of the most widely used in Europe. This particular turbine has been the subject of measurements reported in commercial reports (e.g., Nedwell *et al.*, 2011a,b) and their general characteristics were summarised by Cheesman (2016), although the existing data come from a range of snapshot measurements. In general, most of the data reported in the literature were collected as a series of discrete measurements, generally a few minutes in length, with the collective measurement time spanning a few hours or days. Some of the earlier studies, however, comprised longer term data collection, although data analysis concentrated on subsets of the measured data (e.g., Degn, 2000; Betke *et al.*, 2004). One study focussed on particle

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motion measurements from an offshore wind turbine (Sigray and Andersson, 2011).

The sound associated with wind turbine operation has, in general, been described as continuous in nature, and characterised by one or more tonal components typically at frequencies below 1000 Hz (Degn, 2000; Betke *et al.*, 2004; Madsen *et al.*, 2006; Wahlberg and Westerberg, 2005; Tougaard *et al.*, 2009; Sigray and Andersson, 2011). For turbines with a staged gearbox system, the noise output has been found to vary with wind speed, and wind-driven turbine parameters, including blade revolution, and gearbox and generator rate of operation (Madsen *et al.*, 2006; Betke *et al.*, 2004; Sigray and Andersson, 2011). The correlation of mechanical vibrations of the turbine tower with sound pressure and particle motion measurements in the water column demonstrated by Lindell (2003), and Sigray and Andersson (2011), respectively, corroborated the view that the origin of turbine noise lie in mechanical vibrations in the nacelle, which are transmitted down to the turbine foundation, and originate from the rotation of the wind-powered components in the nacelle. This has been supported with modelling (Marmo *et al.*, 2013).

Some of the previous studies have investigated the relationship between wind speed induced rotation of the turbine components and the radiated underwater noise characteristics during particular wind conditions (Lindell, 2003; Betke, 2004; Tougaard *et al.*, 2009; Sigray and Andersson, 2011), but none examined the temporal variations over a full range of operational conditions. The methodology adopted for this paper allows acoustic measurement data of the sound radiated into the water to be obtained for nominally identical wind turbines, within the same wind farm, over their full range of operational states. The acoustic characteristics of the sound radiated into the water from two individual turbines for a period of 21 days are therefore quantified over the turbine's full power envelope from the cut-in wind speed, through ramp up of the turbine output power, to its maximum operating power and its cut-out wind speed. These are new, robust data, which are not based on snapshot measurements, and that have been obtained with calibrated instrumentation demonstrated to have a suitably low noise floor for measuring the acoustics conditions present during the study. The results provide detailed acoustic characteristics of an operational offshore wind turbine, and show a relatively complex relationship between the sound radiated into the water and wind speed, particularly around the optimal operating wind speed for the turbine. No attempts are made to estimate the sound field at any other position than those measured, and it is not the purpose of this paper to make any assumptions about the potential for impact on marine fauna, although the reference data presented in this paper are expected to facilitate improved confidence in such assessments.

II. MEASUREMENT LOCATION AND SET UP

A. Wind farm

The measurements were performed at the Sheringham Shoal offshore wind farm, which is located in the UK coastal waters, about 20 km offshore of the Norfolk coast. It

comprises 88 wind turbines, each with a 3.6 MW power rating. Figure 1 shows the offshore wind farm layout and individual wind turbine positions. The turbine model used throughout the offshore wind farm is the Siemens SWT-3.6-107 (Siemens, Germany), supported by 4.2 to 5.2 m diameter steel monopiles. The turbine has a three blade rotor, and is equipped with a three stage planetary/helical gearbox, with 1:119 ratio. It operates on a variable rotor speed regulation at 5 to 13 rpm, and reaches the nominal maximum power output of 3.6 MW at wind speed of 13 to 14 ms^{-1} . A wind speed of between 3 and 5 ms^{-1} is required to generate power (cut-in speed), and the turbine cut-out wind speed is 25 ms^{-1} .

The seabed around the wind farm is generally coarse sediment with the foundations predominantly installed in layers of clay, and sand, with some of the foundations terminating in a chalk layer. The nominal water depth across the wind farm site varies between around 16 to 22 m with tidal variations resulting in up to around 4 m rise in water level, depending on the time of the year. The bathymetry within the wind farm is relatively uniform compared with the areas surrounding the wind farm site, which are characterised by both deeper channels and intermittent sandbanks. The deeper areas are frequented by shipping traffic that runs in a roughly east-westerly direction approximately 10 km north and about 6 km south of the offshore wind farm.

B. Measurement equipment

All acoustic measurements reported here were obtained using two DSG-Ocean Acoustic Dataloggers (Loggerhead Instruments), configured to log data directly to a digital solid state recording device. Prior to use, the acoustic pressure sensitivity and acoustic equivalent noise floor of the instrument were tested. The sensitivity tests were performed in a 5 m deep cylindrical test tank with a 5.5 m diameter by comparing the DSG-Ocean Acoustic Dataloggers to a reference hydrophone (Reson TC4040, Teledyne Reson, Denmark), which had previously been calibrated traceable to national standards at the National Physical Laboratory (NPL). During the calibration, the reference hydrophone and the DSG-Ocean

FIG. 1. (Color online) Schematic of the offshore wind farm constituting 88 wind turbines and two offshore meteorological mast installations (circles). Measurements were obtained about 50 m west from a turbine location, for turbine A1 and A5 whose positions within the windfarm are marked by a cross.

Acoustic Dataloggers were precisely positioned to be at the same point in the acoustic field of the source transducer. The tests were performed for a range of discrete frequency tone-bursts from 1 to 40 kHz, in 1 kHz steps. The tone-burst length was chosen to allow measurements to be performed on the steady-state portion of the waveform before the arrival of reflections from the boundaries of the tank, thus approximating a free-field as described in IEC (2006). To test the lower frequencies sensitivity of the DSG-Ocean Acoustic Dataloggers, a comparison against a reference microphone was performed in a closed chamber coupler system. As the dimensions of the chamber are substantially smaller than the wavelength of the sound, the pressure change in the chamber is uniform throughout the chamber. This allowed testing of the DSG-Ocean Acoustic Datalogger sensitivity between 25 Hz and 400 Hz.

The tests showed that the sensitivities of the two DSG-Ocean Acoustic Datalogger devices agreed within around 1 dB of each other, but that differences in sensitivity could be expected from the supplied nominal sensitivity of between 1 and 2.5 dB between 1 and 10 kHz. The testing between 25 and 400 Hz showed similar differences with a consistently lower measured sensitivity than the nominal value provided by the manufacturer. The nominal sensitivity provided and the sensitivity obtained during testing both included the hydrophone sensitivity, gain, and other signal processing on the DSG-Ocean Acoustic Datalogger devices.

It should be noted that the free-field measurements performed on the DSG-Ocean Acoustic Datalogger will include multi-paths or reflections from the body of the device, which will have a frequency dependent effect on both the sensitivity and the directivity of the device (Hayman *et al.*, 2016). This will also be present when the device is used *in situ*, but would not be included in the low-frequency coupler measurements. Given the uncertainty associated with the actual *in situ* response of the device, or its precise orientation to source, this paper reports the absolute sound pressure levels using the supplied nominal sensitivity, and potential for uncertainty should be noted.

To determine the suitability of the DSG-Ocean Acoustic Datalogger for the measurement of underwater sound radiated from an operational turbine, the acoustic equivalent noise floor of these devices was measured in an acoustic test chamber which has a measured acoustic noise floor generally less than 0 dB re 20 μPa with A-weighting applied. These tests demonstrated that the devices under test had acoustic equivalent noise floor levels comparable to sea state zero levels published by Wenz (1962), for the relevant frequencies, which can be considered sufficiently low for the measurement of sound radiated from operational wind turbines which are situated in areas of sea where higher sea-states would generally be expected to prevail.

C. Measurement procedure

Whilst these measurements were performed as part of a broader requirement to carry out measurements of the underwater sound radiated from the operational wind farm, this paper describes work specifically to measure the variation in

the underwater acoustic characteristics of the wind turbines during varying operating states, i.e., rotational speed and wind speed. To do this, underwater sound measurements were obtained during April and May 2013, at two locations adjacent to two different wind turbines. The turbine locations are indicated in Fig. 1 and labelled according to their designated unique identifier within the wind farm (A1 and A5, respectively). The turbines A1 and A5 are located in a nominal water depth of about 16 and 19 m, respectively. Each DSG-Ocean Acoustic Datalogger was tethered from a 75 kg anchor weight, approximately 50 m from each turbine, and floated around 4 m above the seabed using a small sub-surface float around 2 m above the recording unit. The distance between turbine and acoustic recorder deployment position was determined using nautical charts and Geographic Information System positioning information, and confirmed by laser ranging relative to turbine. The location of the anchor weight was marked with a surface float on a separate line to ensure that the recorder and hydrophone were decoupled from the surface motion. The autonomous recorders were left in place to measure the underwater sound pressure over a period of 21 days, using a sample rate of 7017.54 samples per second, default system gain of 20 dB and a 16-bit digital dynamic range, providing a maximum measurement bandwidth of approximately 3.5 kHz. The recorders were configured to acquire data for 30 min, with a 1 min pause before recording again, and the data were stored in an uncompressed WAV file format. It should be noted that all acoustic metrics were chosen to be consistent with ISO (2016).

D. Non-acoustic data

Turbine operational information was provided by Scira Offshore Energy, Ltd. for a number of parameters, including wind speed (around 80 m above the sea surface), and rotational speed of turbine and generator. The data were provided as discrete values recorded every 10 min for the duration of the acoustical measurements. The tidal height information was obtained from the British Oceanographic Data Centre, from the tidal gauge for Cromer, at 15 min intervals.

III. RESULTS AND ANALYSIS

A. Analysis method

All data were analysed in MATLAB 11b (v7.13.0.564, Mathworks, Inc.). The measured acoustic data at each of the autonomous acoustic recorders have been analysed for a period when the recorders were deployed underwater. The time domain data were converted into mean-square sound pressure spectral density (or power spectral density) using Welch's method (Welch, 1967), before applying corrections for the hydrophone sensitivity as a function of frequency across the entire frequency range of interest and for the system gain. Unless otherwise stated, power spectral density level, with units of dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$, will be used as a proxy for mean-square sound pressure spectral density level. Similarly, power spectral level will be used as a proxy for mean-square sound pressure spectral level with units of dB re 1 μPa .²

Each 30 min recording file was broken down into three, 10 min periods, analysed using the Welch's method for a 1 s non-overlapping Hanning window for a 10 min record length. For convenience of showing the complete dataset in spectrogram displays, all 30 min segments have been plotted as a continuous spectrogram over the 21-day period by removing the 1 min recording pause between each 30 min recording file. It should be noted that the use of a 1 s window will result in higher uncertainty of the lower frequency bands and for this reason, measurement data below 10 Hz have generally been excluded. One-third octave bands (base 2) were calculated to be consistent with ANSI S1.1-1986 (ASA 65-1986) (American National Standards Institute, 2008). Broadband acoustical data are calculated as sound pressure level (SPL), also known as root-mean-square sound pressure level, for a bandwidth between 40 Hz and the Nyquist frequency. The SPL was derived from the mean-square sound pressure spectral levels averaged over 10 min as described above, and is reported as an un-weighted quantity.

B. Turbine operational data

The non-acoustic data for wind speed and turbine operation showed a strong positive association. This is exemplified in Fig. 2 where the turbine rotational speed, wind speed and generator speed are plotted over the entire deployment duration. As the wind speed increased, the generator and rotor revolutions increased, plateauing above about 1600 and 13 rpm, respectively, when nominal power generation was reached at around 13 to 14 ms^{-1} winds.

The maximum measured wind speed was 27.2 ms^{-1} , and was simultaneously logged at both turbines on April 18. The corresponding wind speed rotation and generator speed were, 13 rpm and 1619 rpm, respectively. The lowest logged wind speed was 0 ms^{-1} . This was observed on various occasions throughout the deployment duration, and typically did not persist. The wind speed was most frequently logged between 5 and 8 ms^{-1} , and for much of the time the logged values remained below 14 ms^{-1} .

C. Acoustical data

The top panel in Figs. 3 and 4 shows spectrograms for the measured acoustical data obtained at the two wind turbines. These were obtained using the method described in

FIG. 2. (Color online) The time series data for wind speed, rate of turbine blade rotation and the turbine generator speed for turbine A1 (top) and A5 (bottom). The data are plotted for the duration of acoustical data analysed and presented here.

FIG. 3. (Color online) Spectrogram of underwater sound measured about 50 m from wind turbine A1 showing the frequency and amplitude during the 21-day deployment (top). The spectrogram display has been plotted up to 500 Hz for clarity. The lower panel shows the maximum mean-square sound pressure spectral density level (power spectral density level) between 100 and 170 Hz plotted alongside the corresponding frequency data.

Sec. III A to show the power spectral density level for each turbine as a function of time over the duration of the measurement period (21 days).

The power spectral density level analysis captures the turbines operating across a range of the power generating conditions from their minimum to maximum, and also includes periods when wind farm servicing vessels were on site. For both turbines, the spectrograms show that the acoustic power is concentrated in a narrow range of frequencies, with most tonal energy between 100 and 170 Hz. It should be noted that the precise frequency of this concentrated acoustic power, and its level, varies with time, within this frequency range. Tonal components can also be seen outside of this frequency range, albeit being less readily discernible above the background noise. Periodicity in the spectral and amplitude components can be observed, particularly below 40 Hz, and this is thought to be the result of tidal flow induced vibrations in the autonomous acoustic recorder housing/mounting. For this reason, analysis of tonal components thought to be associated with the turbine operation did not consider frequencies below 40 Hz. This noise contamination is considered further in Sec. IV C.

FIG. 4. (Color online) Spectrogram of underwater sound measured about 50 m from wind turbine A5 showing the frequency and amplitude during the 21-day deployment (top). The spectrogram display has been plotted up to 500 Hz for clarity. The lower panel shows the maximum mean-square sound pressure spectral density level (power spectral density level) between 100 and 170 Hz plotted alongside the corresponding frequency data.

The lower panel in Figs. 3 and 4 shows the maximum power spectral density level, in a 1 Hz band, which falls in the frequency range between 100 and 170 Hz. This is plotted alongside the frequency at which this maximum power spectral density level occurs. The data show that the most prominent tonal frequency component (highest amplitude of around 126 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ and 124 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$, approximately 50 m from turbine A1 and A5, respectively) occurred at around 162 Hz, for a 1 Hz resolution. For most of the time, the maximum level was below 120 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$. In general, the maximum power spectral density level associated with the turbine operation, and the corresponding frequency, was variable over the deployment period. Comparing Figs. 3 and 4 with Fig. 2, it can be seen that the highest power spectral density levels generally coincided with times of higher turbine operational rates. Conversely, the lowest power spectral density levels corresponded with measurement periods during reduced turbine operation.

For clarity, Figs. 3 and 4 only show the power spectral density levels up to 500 Hz as it was determined that most of the acoustic energy that could be associated with turbine operation occurred at frequencies below 500 Hz. The elevated power spectral density levels seen at frequencies between 320 and 330 Hz are thought to be harmonics of the main tonal component at around 162 Hz.

Figures 5–8 show the acoustical data, for turbine A1 and A5, presented as a function of frequency. The measurement data are shown as narrowband (1 Hz) mean-square sound pressure spectral density levels (power spectral density levels) in Figs. 5 and 6, and as mean-square sound pressure spectral levels (power spectral levels) in one-third octave bands in Figs. 7 and 8, to facilitate comparison with previous data. Figures 7 and 8 show data for the maximum measurement bandwidth identified in Sec. II C. For enhanced detail, power spectral density levels (Figs. 5 and 6) are plotted for a narrower bandwidth, between 40 and 400 Hz.

To obtain the sound levels corresponding to a particular turbine operating state, the spectra were pooled into categories

FIG. 5. (Color online) Time-averaged spectral characteristics of underwater noise measured around 50 m from wind turbine A1. The data are shown as mean-square sound pressure spectral density (power spectral density) levels between 40 and 400 Hz. The horizontal axis tick marks occur at 10 Hz intervals. The data are presented for five categories of wind speed conditions: 0–2 ms^{-1} , 3–5 ms^{-1} , 6–9 ms^{-1} , 10–13 ms^{-1} , and >14 ms^{-1} . The corresponding mean rotor speed (rpm) is stated in brackets.

FIG. 6. (Color online) Time-averaged spectral characteristics of underwater noise measured around 50 m from wind turbine A5. The data are shown as mean-square sound pressure spectral density (power spectral density) levels between 40 and 400 Hz. The horizontal axis tick marks occur at 10 Hz intervals. The data are presented for five categories of wind speed conditions: 0–2 ms^{-1} , 3–5 ms^{-1} , 6–9 ms^{-1} , 10–13 ms^{-1} , and >14 ms^{-1} . The corresponding mean rotor speed (rpm) is stated in brackets.

based on wind speed ranging from 0 to 25 ms^{-1} (excluding wind speeds above the cut-off wind speed of the turbine). The average narrowband power spectral density levels and the average one-third octave band spectral levels are shown for five nominal wind speed categories: 0 to 2 ms^{-1} ; 3 to 5 ms^{-1} ; 6 to 9 ms^{-1} ; 10 to 14 ms^{-1} ; and >14 ms^{-1} . These categories were chosen to represent nominal turbine operating parameters related to wind speed, such as the cut-in and cut-out wind speed, and the optimal rated power envelope. The average was obtained for the mean-square sound pressure in each 1 Hz bin and one-third octave bands which occurred for each of these categories over the entire deployment period. The presented average sound levels therefore include measurements of the turbine operating in response to the given wind speed categories for a range of environmental (e.g., tidal height, swell, weather, etc.) and external factors (e.g., presence of other noise sources such as service vessels). The minimum duration on which this average was based was for 54 h of data, and this resulted from the highest wind speed category.

The average power spectral density levels in each of the wind speed categories, measured approximately 50 m from

FIG. 7. (Color online) The average measured mean-square sound pressure spectral level (power spectral level) shown for one-third octave bands between 40 and 3200 Hz. The data were measured at turbine A1 over 21 days, and are presented for five categories of wind speed conditions: 0–2 ms^{-1} , 3–5 ms^{-1} , 6–9 ms^{-1} , 10–13 ms^{-1} , >14 ms^{-1} . The corresponding mean rotor speed (rpm) is stated in brackets.

FIG. 8. (Color online): The average measured mean-square sound pressure spectral level (power spectral level) shown for one-third octave bands between 40 and 3200 Hz. The data were measured at turbine A5 over 21 days, and are presented for five categories of wind speed conditions: 0–2 ms^{-1} , 3–5 ms^{-1} , 6–9 ms^{-1} , 10–13 ms^{-1} , >14 ms^{-1} . The corresponding mean rotor speed (rpm) is stated in brackets.

the turbine, shown in Figs. 5 and 6 increased from approximately 101 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ at a frequency of 162 Hz in the 3 to 5 ms^{-1} category to approximately 118 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ at a frequency of 162 Hz in the >14 ms^{-1} category, for turbine A1 (see Fig. 5). Similarly, for turbine A5 (see Fig. 6), the average power spectral density level measured in this band increased from approximately 94 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ at 162 Hz in the 3 to 5 ms^{-1} category to approximately 118 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$ at 162 Hz in the >14 ms^{-1} category; 3 ms^{-1} is the turbine cut-in wind speed, and the turbine cuts out at 25 ms^{-1} .

Figures 7 and 8 show the same data as that shown in Figs. 5 and 6, respectively, but converted into the one-third octave band power spectral levels, and are extended in frequency range to include the maximum available frequency measured.

In the narrowband analysis shown in Figs. 5 and 6, it can be seen that at all wind speed categories, except for the maximum (>14 ms^{-1}), the power spectral density level is spread over a broader range of frequencies, extending below that of the frequency at which the maximum power spectral density level occurs. Closer inspection of the data, particularly of the spectrograms shown in Figs. 3 and 4 and comparison of these with Fig. 2 for turbines A1 and A5, indicates that there is a noticeable variability in the tonal signals generated at the lower wind speeds, which when averaged for all the measurement data for a given wind speed category manifest as a spreading across bands, for 1 Hz bands as in Figs. 5 and 6, and for one-third octave bands as in Figs. 7 and 8. When analysed in one-third octave bands, the spreading of this acoustic power means that there is potential for the power spectral level in the 160 Hz band to be higher for the 10 to 14 ms^{-1} wind speed category than the highest wind speed category, despite the latter being associated with the maximum narrowband power spectral density level. The reason for this variability in frequency characteristics when the wind turbine generator power is ramping up is not clear. The wind turbine considered in this study is described in Sec. II A, and it should be noted that the turbine is designed to have a maximum rotor speed of 13 rpm. The turbine will regulate this at wind speeds above the wind speed at which it

is rated for nominal power by adjustment of the turbine blade pitch, i.e., above a certain wind speed the rotor speed will not increase. The maximum rotor speed will result in a fundamental frequency around 0.2 Hz, with potential for higher frequencies resulting from the gear meshing and generator operation. The generator operated at speeds up to around 1640 rpm which would be expected to produce a fundamental frequency component of around 27 Hz, with potential for harmonics of this fundamental frequency. Whilst it is difficult to identify what gearbox mesh frequencies would be generated without a detailed understanding of the gearbox, it is likely that the frequency component around 162 Hz originated from the gearbox.

When analysed in one-third octave bands, there is very little broadband increase in the power spectral level, with most of the increase occurring only in the 160 Hz band. However, when compared with the narrowband analysis it can be seen that there are a number of frequencies which increase with wind speed or generator speed, in addition to the dominant frequency component around 162 Hz. The tonal frequency components are important characteristics of the sound radiated into the water, which increase notably with wind speed and generator speed, and much of this information is lost when analysed and displayed in one-third octave bands.

The broadband root-mean-square sound pressure level (hereafter SPL), calculated as described in Sec. III A, is shown as a function of integer wind speed bins between 0 and 28 ms^{-1} in Figs. 9 and 10, for turbine A1 and A5, respectively. The figures show an initial general increase in the SPL from a wind speed of 1 to 4 ms^{-1} . This increase may be due to an increase in wind driven sea-state. The SPL values at wind speeds below 1 ms^{-1} are anomalous as they would be expected to be lower in value. It is possible that this is noise radiated from the turbine whilst it is not operational. Another possible explanation for the elevated SPL at wind speeds below 1 ms^{-1} could include a potential increase in vessel activity around the wind farm during calm conditions. For both turbines, a step increase in the SPL was observed between 4 and 5 ms^{-1} , which is expected to be related to the wind turbine commencing to produce power. For this specific wind turbine, a wind speed of between 3 and 5 ms^{-1} is required to generate power (cut-in speed).

FIG. 9. Broadband sound pressure level (SPL) as a function of wind speed shown as the average, and the 5% and 95% percentile for wind turbine A1. The wind speed is pooled in 1 ms^{-1} bins, and the SPL is calculated between 40 Hz and the Nyquist frequency, and averaged over a 10 min period. A single data point was available for wind speeds exceeding 25 ms^{-1} .

FIG. 10. Broadband sound pressure level (SPL) as a function of wind speed shown as the average, and the 5% and 95% percentile for wind turbine A5. The wind speed is pooled in 1 ms^{-1} bins, and the SPL is calculated 40 Hz and the Nyquist frequency. A single data point was available for wind speeds exceeding 25 ms^{-1} .

Beyond this, there is a general increase in the SPL with increasing wind speed. This peaks at a wind speed of around 9 to 10 ms^{-1} , before the SPL begins to show a gradual decreasing trend with increasing wind speed. The SPL reaching its maximum around a wind speed of 9 to 10 ms^{-1} can be explained by the relationship between the wind speed and the rotor speed, and the generator speed. Figures 11 and 12, show plots of the generator speed and rotor speed as a function of wind speed for turbines A1 and A5, respectively. These plots indicate that at a wind speed of around 7 ms^{-1} , the rotor and the generator broadly reach their maximum rotational speed and appear to plateau beyond a wind speed of around 11 to 12 ms^{-1} . This does not, however, explain the decrease in the SPL beyond 9 to 10 ms^{-1} winds. The narrow-band analysis, used to construct Figs. 5 and 6, and which is provided in the supplementary material,¹ shows that the highest mean-square sound pressure spectral density levels occur at a wind speed of about 12 to 14 ms^{-1} . This is consistent with what might be expected from the turbine design specification, which states that the nominal maximum power output of this type of turbine is achieved at a wind speed of 13 to 14 ms^{-1} . Without a detailed knowledge of the gearbox operation and its behaviour under different operating conditions, it is not possible to provide a detailed analysis, with

FIG. 11. Wind turbine rotor and generator speed plotted as a function of wind speed, for wind turbine A1. The rotor speed and the generator speed data were available as integer values, and the wind speed to one decimal place.

FIG. 12. Wind turbine rotor and generator speed plotted as a function of wind speed, for wind turbine A5. The rotor speed and the generator speed data were available as integer values, and the wind speed to one decimal place.

any certainty, on the causes of the complex tonal characteristics of the acoustic data. It should also be noted that the characteristics of the sound radiated into the water are tonal in nature, and the broadband SPL is a simplistic way of assessing the total sound output as a function of wind speed. The mean-square sound pressure spectral density levels shown in Figs. 5 and 6, and provided in the supplementary material,¹ are expected to be more informative.

IV. DISCUSSION

A. Applicability of data

The acoustical data from the two offshore wind turbines measured as part of this study show apparent differences between the two nominally identical turbines, which cannot be easily described by differences in the foundation which are very similar, the substrate in which the foundation terminates, nor the acoustic propagation. The differences are evident in the tonal characteristics of each of the turbines, particularly around wind speeds between 6 and 9 ms^{-1} . Whilst it is not possible to be certain, it is thought that this is due to slight differences in the gearboxes operation or the power regulation of the two turbines. Turbine A1, which shows higher mean-square sound pressure spectral levels at frequencies above a few hundred hertz, was understood by the authors to have reported operational errors to the wind farm control centre, although the nature of the error is unknown. This indicates that nominally identical turbines, operating within the same wind farm or similar environmental conditions, at the same rotational speed, etc., cannot be assumed to be acoustically identical. Despite this, the overall levels measured at the turbines are similar, and the tonal characteristics at the optimal operating power are comparable between the turbines. It should be noted that differences between the turbines might be expected due to differences in the measurement set-up (variability in position and depth of the acoustic recorders), system characteristics, water depth, operational state of neighbouring turbines, and the presence of vessels, etc. Whilst the agreement between the two turbines is relatively good, the presented data do show differences between the turbines and can only be considered to

be representative for the turbines as measured. Care should be taken if extrapolating these data to be representative of operational offshore wind turbines, or indeed a Siemens SWT-3.6-107 turbine. Other studies have shown that the foundation type is an influencing factor on the acoustic characteristics of the sound radiated from the structure (Marmo *et al.*, 2013; Norro *et al.*, 2015), and alternate turbine types would also be expected to have notably different characteristics. For example, for turbine types that operate at a constant rate of revolution, the spectral characteristics of the turbine noise would be expected to remain relatively constant, with only the level varying with wind speed. This has been reported by Tougaard *et al.* (2009) for empirical data, and shown by Marmo *et al.* (2013) using numerical modelling. Sigray and Andersson (2011) reported a change in the turbine output characteristics in relation to its operational state. They observed the largest amplitudes for a moderate wind speed at 6 ms^{-1} rather than at full operating wind speed, which differs from the findings of Lindell (2003) who obtained measurements at the same site, and found the highest levels to correspond with wind speed. Sigray and Andersson (2011) suggested a gearbox replacement as the most likely explanation for this discrepancy.

B. Contributing environmental variability

Other than the expected measurement uncertainties, the key factors which would have caused variability in the data presented here are the background noise, tidal variations, and the presence of vessels in the vicinity. As ambient noise is expected to increase with surface agitation and thus wind speed (Wenz, 1962), it is likely that the ambient noise will increase as the generating output, and therefore the radiated noise, of the wind turbines increases. This has been shown by Tougaard *et al.* (2009) who reported higher signal-to-noise ratio between turbine and background noise for calmer weather and wind speed conditions, rather than in the case where highest turbine noise levels were reported. However, it should be noted that this was only reported in terms of one-third octave bands and the change in signal-to-noise ratio may differ for narrowband analysis where a tonal signal might be expected to show a greater increase relative to the ambient noise. Despite the measurement system having a sufficiently low noise floor, it was not possible in the measurements reported in this paper to observe a significant difference in the ambient noise which could be attributed to the wind speed. It is possible this is due to sea-state not being the dominant contributor to the ambient noise in the study location during the time of the measurements and over the frequency bandwidth used. Tidal height variation would also be expected to effect the amount of sound energy radiated into the water by varying the extent of the foundation and transition piece exposed to the water column. The measurement arrangement used here, i.e., one measurement depth and position, was insufficient to establish any difference due to tidal height. It should also be noted that local vessel activity, in particularly the wind farm service vessels, was also related to the tidal height due to access to the local port being tidal limited.

FIG. 13. (Color online) Spectrogram of underwater acoustical data measured at turbine A1 with tidal data plotted for comparison. The data are shown below 40 Hz, and zoomed-in on a 4 day section for greater detail. The tidal data were obtained from a British Oceanographic Data Centre tidal gauge for Cromer. This is located some distance from the wind farm, and would not be expected to be perfectly time-synchronised with the tidal conditions at the wind farm. However, general temporal character may be compared. The elevated noise levels are thought to correspond to the tidal flow during ebb and flood tide. The tidal data are shown at 15 min resolution.

C. Tidal flow induced noise

The tide did, however, have a significant effect on the background noise, with peaks in the noise spectra, particularly below around 40 Hz being correlated with the tidal changes, as shown in Fig. 13. This shows low frequency sound fluctuations generally corresponding with the periodic nature and duration of the ebb and flow tide, interspersed with relatively short periods of reduced sound levels that were of similar duration as periods with low tidal flow (peak and low tide). This is strongly believed to be a result of the tidal flow on the measurement system, specifically flow induced vibrations in either the mounting system, or the hydrophone support, and not a result of changes in the ambient noise nor radiated noise from the turbine, and cannot be correlated with vessel activity.

D. Limitations related to seabed vibration and sound particle motion

Other routes for turbine noise to enter the water column may be through the air-water interface or through the seabed-water interface. For wind turbine foundations terminated in the seabed, structural vibrations will be expected to transmit into the water via the seabed. However, the measurement data presented here were measured in close proximity to the turbine and so propagating waves in the water column, which originate in the seabed, would not be expected, although the detection of pressure variation from low-frequency interface waves in the seabed cannot be ruled out. Furthermore, the sound particle motion was not measured, which is an important consideration when assessing noise impacts on marine fish and invertebrates, known to respond to particle motion (Popper *et al.*, 2014; Mooney *et al.*, 2010).

V. CONCLUSIONS

Underwater sound measurement data are presented from two 3.6 MW, Siemens SWT-3.6-107, operational wind

turbines over their full operating envelope from the cut-in wind speed, through ramp up of the turbine output power, to its maximum operating power and its cut-out wind speed, obtained over a period of 21 days, in a water depth of about 20 m, with the monopole turbine foundation terminating in a layer of chalk. The data show that the sound radiated into the water was characterised by a number of tonal components, within the measurement bandwidth, primarily related to the gearbox, with variation in amplitude which varied with wind speed, and thus rotor, and generator speed. Measured about 50 m from turbine A1 and A5, the maximum mean-square sound pressure spectral density level at around 162 Hz was 126 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$, and 124 dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$, respectively. Other tonal components were also present, notably at frequencies between about 20 and 330 Hz, albeit at lower amplitudes. An average broadband sound pressure level of 126 dB re $1 \mu\text{Pa}$ and 128 dB re $1 \mu\text{Pa}$ was calculated at wind speeds around 10ms^{-1} for turbine A1 and A5, respectively, with corresponding 5th and 95th percentile values of 114 and 129 dB re $1 \mu\text{Pa}$ and 123 and 131 dB re $1 \mu\text{Pa}$. The measurements show that the sound radiated into the water and the spectral characteristics of the sound are dependent on the operating parameters of the wind turbine, i.e., the rotor and generator rotational speed resulting from variations in the wind speed. Across the operational envelope of the turbine, a change in the mean-square sound pressure spectral density level as high as 20 dB and higher was observed. No broadband sound in the data could be attributed to the wind turbine noise. Above the cut-in wind speed, the sound pressure level and mean-square sound pressure spectral density level increase with the wind speed, until the turbine approaches its nominal power rating. At around 13ms^{-1} wind speeds the mean-square sound pressure spectral density levels of the main tonal peaks more or less plateau, and the sound pressure levels shows a gradual decrease with wind speed beyond about 9 or 10ms^{-1} wind speed. The differences in the measured sound radiated from the two turbines indicates that caution is required if assuming that nominally identical wind turbines within a wind farm are acoustically identical, although the overall measured levels were similar.

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¹See supplementary material at <http://dx.doi.org/10.1121/1.4964824> for tabulated mean-square sound pressure density levels for each integer wind speed, and provided for each of the two turbines individually.

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