## Beyond equilibrium: Re-evaluating physical modelling of fluvial systems to represent climate changes

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#### 23 Abstract

24 The interactions between water, sediment and biology in fluvial systems are complex and driven by 25 multiple forcing mechanisms across a range of spatial and temporal scales. In a changing climate, 26 some meteorological drivers are expected to become more extreme with, for example, more 27 prolonged droughts or more frequent flooding. Such environmental changes will potentially have 28 significant consequences for the human populations and ecosystems that are dependent on 29 riverscapes, but our understanding of fluvial system response to external drivers remains incomplete. 30 As a consequence, many of the predictions of the effects of climate change have a large uncertainty 31 that hampers effective management of fluvial environments. Amongst the array of methodological 32 approaches available to scientists and engineers charged with improving that understanding, is 33 physical modelling. Here, we review the role of physical modelling for understanding both biotic 34 and abiotic processes and their interactions in fluvial systems. The approaches currently employed 35 for scaling and representing fluvial processes in physical models are explored, from 1:1 experiments that reproduce processes at real-time or time scales of  $10^{-1}$ - $10^{0}$  years, to analogue models that 36 compress spatial scales to simulate processes over time scales exceeding  $10^2$ - $10^3$  vears. An 37 38 important gap in existing capabilities identified in this study is the representation of fluvial systems over time scales relevant for managing the immediate impacts of global climatic change;  $10^1 - 10^2$ 39 40 years, the representation of variable forcing (e.g. storms), and the representation of biological 41 processes. Research to fill this knowledge gap is proposed, including examples of how the time 42 scale of study in directly scaled models could be extended and the time scale of landscape models 43 could be compressed in the future, through the use of lightweight sediments, and innovative 44 approaches for representing vegetation and biostabilisation in fluvial environments at condensed 45 time scales, such as small-scale vegetation, plastic plants and polymers. It is argued that by 46 improving physical modelling capabilities and coupling physical and numerical models, it should be 47 possible to improve understanding of the complex interactions and processes induced by variable 48 forcing within fluvial systems over a broader range of time scales. This will enable policymakers

49 and environmental managers to help reduce and mitigate the risks associated with the impacts of

50 climate change in rivers.

*Keywords: fluvial, climate change, physical modelling, review, floods, ecosystems* 

#### 54 1. Introduction

55 Global climate change is a grand challenge facing the Earth across numerous spatial and temporal 56 scales (IPCC 2014; EEA 2017) and the supply of water through the river networks is critically 57 important for the Earth's population (de Wit and Stankiewicz 2006). Expected impacts of climate change in fluvial and fluvially-affected systems such as river deltas and estuaries (Figure 1) include 58 59 altered hydrological regimes and sediment fluxes (Nijssen et al. 2001; Syvitski et al. 2005), 60 variations in biota distribution and growth patterns (Harley et al. 2006), and more frequent extreme events such as storm surges (Lowe and Gregory 2005), river floods (Garssen et al. 2015) and 61 62 droughts (Garssen et al. 2014). Understanding and adapting to these potentially irreversible and 63 detrimental impacts associated with new rates of environmental change and shifts in the frequency 64 and magnitude of events associated with climate change is therefore a fundamental priority for 65 potentially vulnerable fluvial environments, especially in regions where the human population are dependent on the local water supply (de Wit and Stankiewicz 2006). In fact, management of fluvial 66 67 environments presents challenges in a changing climate, and requires an improved understanding of 68 the feedbacks and interactions between the driving mechanisms at work.



71 Figure 1: Schematic diagram to highlight the environments within the scope of this review paper, with 72 an estuarine environment shown in (A) and a deltaic environment shown in (B). Potential climate 73 change impacts in these systems are identified. See Table 1 for details of expected changes in the 74 environments induced by climate change.

75 Physical modelling is an important tool for research in fluvial systems and an established 76 technique for the design and testing of hydraulic structures. The high degree of 77 experimental control in physical scale models allows for the simulation of varied, or rare, 78 environmental conditions and hence measurements of conditions which cannot be 79 measured in the prototype (i.e. the real site to be modelled). Moreover, physical modelling 80 provides an essential link between field observations and theoretical, stochastic and 81 numerical models which are required to predict the impact of environmental changes on 82 aquatic ecosystems (Thomas et al. 2014). Physical modelling can therefore play a key role 83 in the development of a better understanding of climate change impacts by improving our

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- 84 ability to predict these impacts and, in turn, help adaptation to climate change-related
- challenges (Frostick *et al.* 2011; *et al.*2014).
- 86 Table 1: Details of expected climate change induced impacts on fluvial and fluvial-affected estuarine
- 87 and deltaic environments. Physical modelling studies can be used to understand these processes and
- 88 test possible adaptation strategies.

Climate induced	Predicted change	Associated impact on estuarine	Source		
change in forcing		and fluvial environments			
Global mean surface temperature	By 2100: 0.3-1.7 °C temp. rise (scenario RCP2.6*) 2.6-4.8 °C temp. rise (scenario RCP8.5*)	Implications for vegetation growth in all environments	IPCC (2014)		
Sea level rise	By 2100: 0.26-0.55 m (scenario RCP2.6) 0.45-0.82 m (scenario RCP8.5) 70% of coastlines worldwide experience change within 20% of global mean	Drowning of estuarine environments. Encroachment of saline water and associated impacts on biota. Increased aggradation of river deltas, accelerated channel and floodplain deposition and to higher channel avulsion frequency	IPCC (2014), Jerolmack (2009)		
Storm surges	Largest increase in 50 year return period storm-surge height at UK coastline = 1.2 m (Scenario A2)	Increased risk from hazards (e.g. coastal flooding, coastal erosion) associated with storm surge events	Lowe and Gregory (2005)		
Precipitation	Scenario RCP8.5: Increase in mean precipitation in high latitudes and equatorial Pacific. Decrease in mean precipitation in mid-latitudes. Increase in extreme precipitation over most of mid- latitude landmasses and wet tropical regions become more intense and more frequent	Rivers: increased frequency and magnitude of higher peak flows, and possible prolonged drought periods with associated impacts for riparian vegetation distribution. Potential shifts in timing of seasonal hydrological regimes	IPCC (2014), (Garssen <i>et al.</i> 2014; <i>et al.</i> 2015)		
Waves	Latitude dependent: 0.6-1 m increase in 20 year return period wave height between 1990- 2080 in NE Atlantic. Wave with 20 year return period in 1990 will have 4-12 year return period in 2080	Modification of the dynamics of estuarine and coastal systems	Wang <i>et al.</i> , (2004)		

90 greenhouse gas emissions. RCP2.6 refers to a stringent mitigation scenario, and RCP8.5 refers to a

- scenario with very high greenhouse gase emissions (IPCC, 2014).
- 92

- 93 Physical scale models are a key tool to simulate and investigate complex processes and
- 94 feedback mechanisms, with experimental designs that reflect the spatial and temporal 6

95 scale of the problem under investigation. Such techniques have been used for more than 96 100 years to investigate the interaction among flow, sediment transport, morphology, and 97 interactions with biota, enhancing the understanding of many different and complex 98 sediment transport and morphological processes across different spatial and temporal 99 scales (Kleinhans *et al.* 2015).

100 Physical modelling for climate change adaptation faces the challenge of incorporating, and 101 scaling, non-linear responses across a range of temporal and spatial scales resulting from 102 long-term changes in event frequency and magnitude. Recently, physical models have 103 started to explore the impact of climate change on the aquatic environment by examining 104 boundary conditions that reflect a possible future climate state, often using a simplified 105 representation of the systems (i.e. single grain size sediment, or no biotic elements). In 106 addition to evaluating the behaviour of a system at the final stage of a future climate 107 scenario, work is required that explores the progressive development of the system, 108 including time-varying processes, from one state to another as a consequence of climate change (IPCC 2014; EEA 2017). In particular, the morphology of riverine, deltaic and 109 110 estuarine environments will develop and change over time in response to long-term 111 changing boundary conditions and process rates. To address the challenges related to 112 climate change, it is crucial to develop a further understanding of the complexity of the 113 systems, and how the environments adapt over longer periods of time, whether this 114 change is gradual or sudden, and how they behave under a different climate regime.

In this context, this review will examine current techniques and capabilities in physical modelling experiments for representing climate change induced impacts on aspects of fluvial systems such as hydrodynamics, sediment transport, morphodynamics and ecohydraulics. Firstly, this review provides a technical discussion of different modelling approaches and the formal scaling laws that they obey (section 2), before identifying the challenges that physical models face for representing variable forcing and the impacts of climate change within experiments (section 3). Section 4 7 provides detailed examples of recent innovative approaches at the forefront of the physical
modelling in environmental systems and how these modelling approaches may be enabled in the
future.

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## 125 **2. Scaling approaches and challenges in representing different time**

## 126 scales in physical modelling

Figure 2 presents a schematic overview of different model types and their ability to replicate the relevant spatial and temporal scales of the prototype. In the discussion below, we explain the essence of each of these approaches, the scaling laws that they must successfully achieve and provide some examples of their application for the understanding of fluvial processes and systems.



Figure 2. The relative application of different approaches for physical modelling, with different
approaches being more appropriate for modelling processes over different spatial and temporal scales.
Developed from Peakall et al. (1996).

136 In scaled models, the time passes generally faster than in the prototype, which makes 137 them attractive for the study of climate change impacts. However, as will be outlined below, 138 their design and the interpretation of results can be challenging because the hydrodynamic 139 time scales are generally quite different from those for morphodynamic fluvial adjustments 140 (Tsujimoto 1990), and the scaling of biota is even more uncertain. Models based on both 141 geometrical and dynamic similarity (i.e. by scaling important force ratios; see below) are a 142 well-established approach for designing hydraulic structures at larger spatio-temporal 143 scales while distorted models (models with different geometrical scale ratios in the

horizontal and vertical directions), and relaxed-scale analogue models attempt to
reproduce some selected properties of the prototype (Peakall *et al.* 1996).

146 The scaling laws used to design physical models can be derived based on a dimensional 147 analysis (Buckingham 1914; Barenblatt 2003). An important prerequisite for the design of 148 a physical model is the dynamic similarity that ensures a constant prototype-to-model ratio 149 of the masses and forces acting on the system (Einstein and Chien 1956; Yalin and 150 Kamphuis 1971; Hughes 1993; Frostick et al. 2011), i.e. that the derived dimensionless 151 parameters are equal in model and prototype. Important force ratios defining these dimensionless numbers can be obtained by considering inertia, gravity, viscosity, surface 152 153 tension, elasticity and pressure forces, respectively. A perfect dynamic similarity for all 154 possible force ratios cannot normally be achieved for model scales that deviate from the 155 prototype scale since the same fluid (water) is normally used in both prototypes and 156 models. This means that it is not possible to design a downscaled model so that the 157 relative influence of each individual force acting on a system remains in proportion 158 between prototype and model as outlined by e.g., Yalin (1971); Hudson (1979), de Vries et 159 al. (1990); de Vries, (1993)et al.; Hughes (1993); Sutherland and Whitehouse (1998); 160 Ettema and Muste (2004) and Heller (2011) and. Scale models need therefore to be 161 designed in a way that maintains important force ratios whilst providing justification for 162 neglecting other force ratios. Neglecting force ratios will result in scale effects if the model 163 is operated at boundary conditions where the neglected force ratios are important; in other 164 words, there will be a divergence between up-scaled model measurements and real-world 165 observations. Scale effects become more significant with increasing scale ratio and their 166 relative importance depends on the investigated phenomenon (Heller 2011), i.e. scale 167 effects will have to be accepted.

168 In the following discussion of the different modelling approaches, it is assumed that the 169 model studies are carried out with water as model fluid so that the ratio of fluid properties 10 170 in model and prototype such as fluid density  $\rho_r$ , fluid dynamic and kinematic viscosity 171  $\mu_r$  and  $\nu_r$  respectively are equal to 1; the subscript r denotes the ratio between model (m) and prototype (p). Moreover, scale effects due to fluid temperature will not be considered 172 173 although it is worth mentioning that Young and Davies (1991) used heated water (30° C) in 174 their experiments in order to achieve closer similarity in Reynolds numbers. Finally, 175 although beyond the scope of this review, experiments using dense fluids have been used 176 to study grains at the threshold of motion (e.g. oil (Best 1998) and glycerol (Guerit et al. 177 2014)), and scaling for morphological processes in extra-terrestrial environments is also 178 possible (e.g., aeolian dunes on Mars and Venus (Claudin and Andreotti 2006); 179 morphological development on Mars (Kraal et al. 2008; Marra et al. 2014; Dietrich et al. 180 2017)).

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#### 2.1.1:1 Physical models

Models that replicate the prototype with no reduction in dimensions can be described as 182 183 1:1 physical models (Figure 2). 1:1 models are mainly used to study physical processes at 184 the smallest spatial and temporal scales under controlled conditions. Examples include 185 experiments aimed at replicating flow turbulence structures in open channels to predict 186 incipient motion and sediment transport (Shields 1936; Grass 1971; Nikora et al. 2001; 187 Zanke 2003; Hofland et al. 2005). Full-scale replication of the larger components of rivers 188 such as channels, levees and bars requires a lot of space with associated high operational 189 costs and these experiments are therefore rare. An example of a 1:1 model is provided by 190 which river dike replicated the Smart Levee project in а is (Figure 3. 191 http://www.floodcontrolijkdijk.nl/en/experiments). The full-scale physical model allows for 192 experiments on piping, micro- and macro-stability, and flow slide in the absence of scale 193 effects.

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196 Figure 3. Example of a physical model of a river dike taking a 1:1 approach 197 (<u>http://www.dijkmonitoring.nl/en/projects/</u>).

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#### 2.2. Undistorted models

199 Geometrical similarity means that all scales with dimensions of length *x*, *y*, *z* are equal:  $r_x =$ 200  $r_y = r_z$  (Figure 2), and in *undistorted models* the geometry of the model is consistent with the 201 geometry of the prototype. The most commonly used scaling approach for fluid flow in 202 *undistorted models* is Froude-scaling, which requires similarity in the Froude number in 203 model and prototype:

204 
$$Fr = U/(gh)^{0.5}$$

205 (1)

where *U* denotes the mean flow velocity, *g* the gravitational acceleration, and *h* the water depth. This scaling law, ensuring a constant ratio between inertia and gravitational forces in model and prototype, is most significant for open channel flows and ensures that thewater surface will be adequately replicated in the model (Kobus 1978).

210 Considering a uniform open-channel flow with a fixed bed in a wide channel, i.e. a width to 211 depth ratio > 30 so that the hydraulic radius can be replaced by the water depth h, 212 dimensional analysis results in four important dimensionless parameters, which are the 213 Froude number as defined above, the flow Reynolds number Re = Uh/v (where v is the 214 viscosity), the relative roughness k/h (with k = roughness length scale, which is often 215 expressed in terms of the grain diameter d), and the slope S. Requiring Froude number 216 similarity in model and prototype means that the flow Reynolds-number (Re) will differ 217 between the model and prototype (it can be shown that for Froude-scaled models  $Re_m$  < 218  $Re_{p}$ ). To avoid corresponding scale effects, the flow in both model and prototype needs to 219 be fully turbulent so that viscosity effects are negligible. The roughness (or friction losses) 220 can be scaled considering similarity in the Darcy-Weisbach friction factor or alternatively in 221 the Chézy-coefficient or Manning number, and the model slope equals by definition the 222 prototype slope in undistorted models.

223 Movable bed models represent a two-phase flow with a solid (particles) and fluid phase 224 (Yalin 1959). While the flow is generally Froude-scaled, the similarity in sediment 225 movement depends on a set of additional dimensionless parameters which are the grain Reynolds-number  $\text{Re}_{\star} = v_{\star}d/v$ , densimetric Froude number (Shields-number) 226  $Fr_* = \rho v_*^2 / [(\rho_s - \rho)gd]$ , relative sediment density  $\rho_s / \rho$ , relative submergence h/d, and 227 relative fall speed v<sub>s</sub>/v<sub>\*</sub> (see Yalin 1971; Hughes 1993; Peakall et al. 1996 for details). 228 Peakall *et al.* (1996; 2007) argued that the 90<sup>th</sup> percentile of the sediment grain size ( $D_{90}$ ) 229 230 should be used in the calculation of the grain Reynolds-number (Re\*), as the coarsest 231 grains contribute the most to the definition of the hydraulic conditions due to their impact 232 on the roughness of the sediment surface. Recently, Kleinhans et al. (2017) argued that

percentiles lower than the  $D_{90}$  can be used when the sediment mixture contains a wide range of grain sizes, as long as the percentile used protrudes above the viscous flow sublayer to contribute to roughness. In these definitions,  $\rho$  denotes the fluid density,  $\rho_s$ denotes the sediment density, v the shear velocity, and  $v_s$  the fall velocity. To obtain perfect similitude for sediment transport processes in model studies using water as fluid (i.e.,  $\rho_r = v_r = 1$ ), all these quantities would have to be equal in the model and prototype resulting in:

$$240 Re_{*r} = d_r v_{*r} = 1 (2)$$

241 
$$Fr_{*r} = \frac{v_{*r}^2}{(\rho_s - \rho)_r d_r} = 1$$
 (3)

$$\rho_{s,r} = 1 \tag{4}$$

$$243 \qquad \frac{h_r}{d_r} = 1 \tag{5}$$

244 
$$\frac{V_{s,r}}{V_{*_r}} = 1 = \frac{\sqrt{L_r}}{t_r}$$
 (6)

245  $L_r$  is the horizontal length scale ratio, and  $t_r$  is the hydraulic timescale. Equations (2) – (6) 246 were formulated for unidirectional flow conditions for which the shear velocity can be 247 determined via  $v_* = (ghS)^{0.5}$  so that, for example, equation (3) can be written as:

248 
$$\operatorname{Fr}_{r} = \frac{h_r^2}{\left(\rho_s - \rho\right)_r L_r d_r} = 1$$
 (7)

A general problem encountered in the scaling of shear velocity  $v_{*}$  (or bed shear stress) is that this similitude assumes a flat bed. This is not necessarily the case because the bed topography of most riverine environments is characterized by bedforms or other morphological features (Hughes 1993), i.e. scale effects may be induced if such morphological features are not adequately reproduced or if  $d_r$  deviates from the vertical scale ratio  $h_r$  (Gorrick and Rodríguez 2014). Based on the similarity in *Fr* it becomes possible to derive the hydraulic time scale  $t_r$  (Kobus 1978):

$$256 t_r = \frac{L_r}{\sqrt{h_r}} (8)$$

For a non-distorted model  $t_r = L_r^{0.5}$ , indicating that time related to mean properties of the flow field in the model passes faster than in the prototype.

259 The mechanism for suspended sediment transport differs from the mechanism for bed 260 load transport. This is reflected by the criterion defined by equation (6) corresponding to 261 the ratio of settling velocity to shear velocity, i.e. the Rouse number, which is most 262 important for suspension-dominated models. Such models are more common in coastal 263 modelling applications than in alluvial river studies and require the reproduction of the uplift of particles due to turbulence induced by waves or currents, and their subsequent 264 265 transport in the water column. In this context it is worth mentioning that, in the case of 266 waves, such models require the consideration of different physical parameters in equations (2) - (6) than fluvial bed load models, such as the characteristic velocity  $(qH_b)^{-0.5}$ 267 268 instead of the shear velocity  $v_*$  and the breaking wave height  $H_b$  instead of water depth h 269 (Hughes 1993).

Assuming Froude-similarity for the flow and inserting the corresponding hydraulic time scale given by equation (8) into equation (6) yields:

272  $h_r = L_r$ 

(8)

i.e. the dynamics of the suspended load transport can only be modelled exactly using an undistorted model. Considering all scaling criteria, it is therefore only possible for one transport mode to be modelled following similarity criteria while the other mode will be affected by scale-effects (Hughes 1993). Nonetheless, physical model experiments that simulate both modes of sediment transport have been attempted (Grasso *et al.* 2009). If movable bed models need to be distorted, the distortions should not be so large that the type of sediment transport changes (i.e. from bed load to suspended load or *vice versa*).

When maintaining the similarity in sediment density ( $\rho_{s,r} = 1$  or ( $\rho_s - \rho$ )<sub>r</sub> = 1), undistorted 280 281 models fulfil the criteria given by eqns. (3) to (5) while violating the fall velocity (equation 6) 282 and the grain-Reynolds number criterion (equation 2). The latter corresponds for this model type to  $Re_{\tau} = L_r^{1.5}$  indicating that they should be operated in hydraulic rough 283 284 conditions, i.e.  $Re_* > 70$ , to avoid scale effects arising through viscous forces as  $Re_*$  in 285 prototype conditions will be larger than in the model. Recent work has indicated that the value of  $Re^* > 70$  to define hydraulically rough conditions may be overly conservative, with 286 287 the value potentially as low as 15 being sufficient (Parker, 1979; Ashworth et al., 1996; 288 Kleinhans *et al.*, 2017). An important limitation of this type of model in regard to the scale 289 factor arises from the requirement to scale the sediment with the same factor as the model 290 length scale. If, for example, fine sand is already present in the field, fulfilling this 291 requirement could easily result in using sediments that are cohesive, which generates 292 additional problems due to the different behaviour of cohesive sediments compared to a 293 granular material. To minimize this problem, special materials may be used such as 294 Ballotini® (non-cohesive glass microspheres with diameters as small as 45 µm) or 295 different model types as described below.

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#### 2.3. Distorted physical models

297 Distorted models are characterised by different horizontal and vertical length scales so that 298  $S_r \neq 1$  (Figure 2). The distortion leads directly to scale effects in the flow field (see e.g. Lu et 299 al. 2013; Zhao et al. 2013) and geometric similarity may be replaced by geometric affinity 300 (De Vries 1993). Distortion is not acceptable in a model where the vertical velocity 301 components are important, but vertically distorted models are acceptable for uniform, non-302 uniform and unsteady flow conditions with relatively slow vertical motion (Novak et al. 303 2010). For example, considering scale models of river reaches, the horizontal dimensions 304 involved are commonly much larger than the vertical dimensions and this will lead to 305 unrealistic scale models if the vertical scale ratio  $(h_r)$  is selected equal to the horizontal 16

306 length scale ratio  $(L_r)$  (De Vries 1993). Additional care needs to be taken with regard to 307 potential scale effects due to water surface tension if the water depth in the model is low 308 (Hughes 1993; Peakall and Warburton 1996; Van Rijn et al. 2011) or if the model is 309 operated with varying background water levels (e.g., to simulate tidal effects) because the 310 effect of wetting and drying bank material will change its behaviour (e.g. Thorne and Tovey, 311 1981). The key issue in reproducing mobile bed morphology is sediment mobility. Particle 312 size cannot be reduced to the same degree as the other x, y, z dimensions of the 313 experiment relative to the prototype because properties such as incipient motion and 314 cohesion of silt and clay are significantly different from those of sand and gravel (Lick and 315 Gailani 2004). Given the small water depth and flow velocities in this model type, sediment 316 mobility is typically lower than in the prototype or may even be below the beginning of 317 sediment motion. Three methods have classically been applied to overcome this issue 318 (Kleinhans et al. 2014): i) a vertical distortion of the model leading to increased gradients 319 and reduced surface-tension effects (Peakall et al. 1996); ii) tilting of the bed, which further increases the gradient; or iii) the introduction of lightweight sediment. 320

321 Vertical exaggeration of the model compared to the prototype has a range of effects on 322 sediment transport, morphodynamics and resultant stratigraphy. Stronger bed gradients 323 combined with small water depths affect the threshold for the beginning of sediment 324 motion (Shields 1936; Vollmer and Kleinhans 2007), which cascades into differences in 325 sediment sorting patterns between the model and the prototype (Solari and Parker 2000; 326 Seal et al. 1997; Toro-Escobar et al. 2000; Wilcock 1993; Peakall et al. 2007; Stefanon et 327 al. 2010). In addition, it can be shown analytically that wavelengths, migration rates and 328 amplitudes of river bars are a function of channel width-to-depth, sediment mobility as well 329 as channel curvature, width variations and sinuosity (Struiksma 1985; Seminara and 330 Tubino 1989; Talmon et al. 1995). This implies that any vertical distortion in the scale 331 model will alter the morphology and resultant stratigraphy as seen in the prototype. The

332 introduction of lightweight sediments results in similarity in both Re, and Fr, while violating 333 intentionally the sediment density as well as the relative roughness criterion. As indicated 334 by the name, this type of models makes use of model sediments with a lower density than 335 the prototype sediment. For models focusing on bed load transport it may be reasonable to 336 relax the criterion defined by equation (6). Low (1989) found in experiments with 337 lightweight materials of different specific densities  $1 < \rho_s/\rho < 2.5$  and a grain diameter of d = 3.5 mm that the specific volumetric bed load transport rate  $q_s$  was related to  $v_{*r}/v_{s,r}$  by a 338 simple power relation and that  $q_s \sim v_*^6$  and  $\sim v_s^{-5}$ . Zwamborn (1966) argued that the  $Fr_*$ 339 340 criterion (equation 3) is essentially the same as the  $v_{*r}/v_{sr}$ -criterion and that a good 341 similarity in river morphology can be expected between model and prototype if the latter 342 criterion is used together with an appropriate friction criterion and near similarity in Re. 343 More details in regard to the scaling laws considering or neglecting the fall-speed 344 dependency for such models can be found in Hughes (1993) and Van Rijn et al. (2011).

345 Distorted physical models with vertical exaggeration have been used extensively in the 346 past across a range of scales, including extremely large basin-wide hydraulic models 347 designed for engineering purposes. A notable example is the Mississippi Basin Model 348 (MBM) constructed by the US Army Corps of Engineers (Fatherree, 2004); a physical 349 model of the entire Mississippi river and its core tributaries at a horizontal scale of 1:2000 350 and a vertical scale of 1:100 (Foster, 1971). The MBM was used to study the dynamics of 351 peaks of individual flood hydrographs within the Mississippi basin, such as identifying areas where levees would be overtopped during an expected flood on the Missouri River 352 353 in 1952 (Foster, 1971) and proved to be an invaluable tool in studying the storage and 354 dynamic effects of backwater areas (Louque, 1976). The operating cost of the MBM and 355 similar scaled basin models such as the Chesapeake Bay (Fatherree, 2004) or the San 356 Francisco Bay-Delta Tidal Hydraulic Model (Wakeman and Johnston, 1986), was 357 impractical due to their size, but they demonstrated the ability to accurately replicate the 18

358 dynamics of individual flood events within basins over large spatial scales that is 359 impossible using reach scale physical models.

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#### 2.4. Process-focused physical models

362 Here we introduce the term process-focused physical models (Figure 2) to describe 363 Densimetric Froude models that relax the similitude in Re. (Eq. 2) whilst maintaining similarity in  $Fr_{*}$  (Eq. 3), but do not have a particular target natural prototype in mind. These 364 365 models allow the investigation of the processes and generic planform morphologies such 366 as channel braiding by reproducing fundamental sediment transport processes such as 367 bedload transport and exploring the sensitivity of processes and morphologies to different 368 experimental conditions. Bed sediment must be mobile in the bedload regime to replicate 369 gravel-bed rivers in nature and mobile in the suspension regime to replicate sandbed 370 rivers, which is challenging due to cohesive effects for silt and clay if used to represent 371 scaled down sand (Smith 1998; Hoyal and Sheets 2009). This class of models simplifies 372 the representation of both discharge regimes and sediment properties using simple flow 373 regimes (constant discharge or single events to represent annual floods) and a 374 hydraulically rough bed to minimise scale effects, which conflicts with sediment mobility 375 requirements. This conflict is generally solved by applying a poorly sorted sediment 376 mixture in which the coarsest fraction ensures hydraulic rough conditions (Peakall et al. 377 2007; Van Dijk et al 2012). Examples of process-focused models include the experiments 378 aimed at river meandering by Friedkin (1945) and the braided river experiments by Ashmore (1988). Many practical applications of such models indicate their suitability in 379 380 studying morphodynamic processes within river reaches as well as for coastal 381 environments (Hughes 1993; Willson et al. 2007; Kleinhans et al. 2014).

There is an overlap between distorted models and process-focused models when similitude in *Re*\* may be close to specific natural protoype situations (Figure 2). Similarly, the point at which a process-focused model should be described as an analogue physical model is not always clear since it is not known when simplifications in sediment characteristics or discharge regimes make model behaviour differ significantly from a natural system.

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#### 2.5. Analogue physical models

390 The evolution of river morphodynamics over larger spatial and temporal scales is often 391 investigated in so-called analogue models (Davinroy et al. 2012), which are designed to 392 represent larger prototype environments over longer periods of time (Figure 2). Analogue 393 models are designed to study analogies or 'similarity of process' between the model and 394 prototype and are not designed to keep strict similarity in the above scaling criteria (Hooke 395 1968), although they can theoretically be classified according to the model types defined 396 above. However, the aforementioned model types are generally stricter in terms of 397 similarity criteria than analogue models for which the validation or 'effectiveness' (Paola et 398 al. 2009) depends on the judgement of similitude in bed-sediment movement (Ettema and 399 Muste 2004) or on the operator due to the lack of a specific methodology for describing the 400 degree of morphodynamic and stratigraphic similarity in model studies (Gaines and Smith 401 2002). Yet, well-designed analogue models have been shown to be an essential tool for 402 studying morphodynamic processes and stratigraphic expressions across a wide range of 403 spatial scales for different river channel morphologies and fluvially-affected coastal 404 environments (Bruun 1966; Hudson 1979; Peakall et al. 2007; Wickert et al. 2013; Green 405 2014; Bennett et al. 2015; Yager et al. 2015; Baynes et al., 2018), despite violating the

406 aforementioned scaling rules in many ways (Paola *et al.* 2009; Kleinhans *et al.* 2014;
407 Peakall *et al.* 1996; Kleinhans *et al.* 2015).

408 Due to the large range in spatial and temporal scales covered by *analogue models*, two 409 sub-groups can be identified (Figure 2). First, analogue-reach scale models are process-410 focused physical models with an added degree of scaling relaxation. Examples include the 411 introduction of alfalfa as vegetation into the models as a representation of vegetation 412 effects in nature. A host of experiments has highlighted the important role vegetation can 413 have in controlling bank erosion, river pattern formation and channel mobility under the 414 simplest conditions (Gran and Paola 2001; Tal and Paola 2007; Tal and Paola 2010; 415 Braudrick et al. 2009; Van de Lageweg et al. 2010; van Dijk et al. 2013a; Wickert et al. 416 2013). The addition of fine silica flour in the experiments of Peakall et al. (2007) and Van 417 Dijk et al. (2013b) as the finest sediment into the models as a representation of cohesive 418 silt and clay in nature can also be considered an analogue-reach modelling approach, and 419 has been shown to lead to active meandering systems due to the added cohesion of 420 incorporating fine grained material (Peakall et al., 1996; 2007; Kleinhans et al., 2014). The 421 addition of nutshells has been used to represent low-density and highly-mobile sediment 422 acting as floodplain filler (Tambroni et al. 2005; Hoyal and Sheets 2009; Van de Lageweg 423 et al. 2016; Ganti et al. 2016). Similarly, a wide range of extracellular polymeric 424 substances (EPS) has been introduced into models to represent biological cohesion 425 (Hoyal and Sheets 2009; Kleinhans et al. 2014; Schindler et al. 2015; Parsons et al. 2016). 426 For example, EPS has been used in analogue delta experiments to increase the range of 427 natural morphodynamics processes that can be reproduced, by increasing the cohesion of 428 the sediment material (Hoyal and Sheets 2009). The polymer-sediment mix, developed at 429 the ExxonMobil Upstream Research Company (Hoyal and Sheets 2009) performed best in 430 the presence of clay and sand, and the deltas produced during the experiments had 431 geometries characteristic of natural deltas composed of sandy non-cohesive sediments,

432 allowing experimental investigations of forcing factors such as sea-level rise on channel
433 mobility and shoreline dynamics (Martin *et al.* 2009).

Second, analogue-landscape models represent the spectrum of scale models associated 434 435 with the largest spatial and temporal scales shown towards the top right in Figure 2. Such 436 models typically concern an entire landscape (e.g. delta or mountain range) and aim to 437 explore its evolution across longer (e.g. geological) time scales. River-delta landscape 438 experiments provide an example of this type of scale model (Figure 4). The analysis of 439 these experimental data allowed the identification of a small, but significant, chance for the 440 preservation of extreme events in the stratigraphy due to the heavy tailed statistics of 441 erosional and depositional events (Ganti et al. 2011). This quantified understanding of the 442 evolution of a river delta system under rising base level would only be possible using the 443 analogue-landscape modelling approach, where processes characteristic of larger delta 444 systems are replicated and monitored at high spatial and temporal resolutions that would 445 be impossible in the field.



Figure 4. Example of an experiment using an analogue-landscape modelling approach (Sheets *et al.* 2002; Ganti *et al.* 2011). (a) Schematic of the experimental set up. (b) Photography of the delta after 11 hours of experimental run time. From Ganti *et al.* (2011).

450

## 451 **3.** Challenges representing climate change impacts in physical models

The impacts of climate change, and more broadly, non-constant forcing, will affect fluvial systems over a range of time scales. Increased magnitude of individual events to millennial-scale shifts in long-term forcing dynamics such as the total volume and seasonal variations in annual precipitation and changes in the biological characteristics could have dramatic impacts on the state and 456 functionality of fluvial systems (Wobus *et al.* 2010). This section identifies the current challenges in457 representing these impacts on the fluvial environment using physical models.

458

#### 3.1. Differing timescales of morphodynamic and hydrodynamic processes

Hydrodynamic processes usually occur at a much shorter time scale than morphodynamic processes and, as will be shown below, time scales related to different morphological processes do not necessarily coincide in physical models (Yalin 1971). This can, in turn, result in undesired scale-effects that become more significant with decreasing physical model scale (i.e. of the reproduction of the prototype) (Figure 2).

464 The determination of sedimentological time scales in movable-bed models is difficult and often subjective. In fact, the sedimentological time scale cannot be freely chosen as it 465 466 results from the chosen scales of the other model parameters (Hentschel 2007) and, 467 hence, depends on which scaling criteria are intentionally violated. Moreover, there is the 468 need to distinguish between different time scales for different morphological processes 469 such as individual grain movement  $(t_{sq,r})$  and the evolution of the bed surface in the vertical  $(t_n)$  and horizontal  $(t_{Lr})$  directions, respectively. Corresponding time scales are presented 470 471 in general terms in Table 2.

Time scale	Eq.	Criteria and	Source
$t_{sg,r} = d_r L_r^{0.5} h_r^{-1}$	(10)	- individual grain movement	Yalin (1971)
$t_{sg,r} = L_r h_r^{-2}$	(11)	<ul> <li>individual</li> <li>grain</li> <li>movement</li> <li>similarity in</li> <li>Re.</li> </ul>	Yalin (1971)
$t_{\eta r} = L_r h_r$	(12)	<ul> <li>similarity in</li> <li>dimensionless</li> <li>transport rate</li> <li>similarity in</li> <li>Re-</li> <li>porosity</li> <li>equal in</li> <li>model and</li> <li>prototype</li> </ul>	Yalin (1971)
$t_{\eta r} = L_r^{1.5} d_r^{-1} (1 - \phi)_r$	(13)	- similarity in dimensionless transport rate	Hentschel (2007)
$t_{\eta r} = L_r^{2.5} h_r^{-2} \left( 1 - \phi \right)_r \left( \rho_s - \rho \right)_r$	(14)	- similarity in dimensionless transport rate - similarity in Fr•	Hentschel (2007)
$t_{\eta r} = L_r h_r^{1.5} d_r^{-7/6} \left( 1 - \phi \right)_r$	(15)	<ul> <li>similarity in</li> <li>dimensionless</li> <li>transport rate</li> <li>similarity in</li> <li>Fr*</li> <li>near</li> <li>similarity in</li> <li>Re*</li> </ul>	Tsujimoto (1990)
$t_{Lr} = L_r^{1.5} h_r^{-1}$	(16)	- individual grain movement	Yalin (1971)

473 Table 2. Time scales for bed load dominated models,  $\rho r = \mu r = vr = 1$ , and assuming  $v^* = (ghS)^{0.5}$ .

474

According to Yalin (1971), the movement of an individual bed load grain is governed by the geometrical scale of the particle diameter *d* and the kinematic scale *v*\*, respectively resulting in the time scales  $t_{sg,r}$  defined by equations (10) and (11), where equation (12) results from the additional requirement of similarity in *Re*\*. 479 Considering the temporal development of a movable bed surface in a physical model, different scales in the horizontal and vertical directions need to be taken into account. For 480 481 fluvial environments, the most common approach to derive the time scale for the formation 482 of a movable bed surface is based on the comparison of the model response time to 483 known prototype response times (Vollmers and Giese 1972; Kamphuis 1975; Einstein and Chien 1956). This is typically achieved by considerations of the variation of the bed 484 485 surface level  $\eta$  in vertical direction with time and the volumetric sediment transport rate q, 486 i.e. the Exner equation (Paola and Voller 2005; Coleman and Nikora 2009). Thus, the corresponding time scale can be defined according to Tsujimoto (1990) and Hughes 487 488 (1993):

$$t_{\eta r} = \frac{L_r h_r \left(1 - \phi\right)_r}{q_r} \tag{17}$$

489

where  $\phi$  denotes the porosity of the bed material. A similar formulation can be obtained considering the movement of river dunes assuming their geometrical similarity in model and prototype. Introducing the dimensionless volumetric bed load transport rate  $q_* = q$  /  $(v_*d)$ , equation (17) can be rewritten according to:

494 
$$t_{\eta r} = \frac{L_r h_r (1-\phi)_r}{q_{*r} d_r v_{*r}}$$
 (18)

Assuming similarity in  $q_{*}$  in model and prototype (i.e.  $q_{*r} = 1$ ), equation (18) represents the basis for equations (12) to (15) in Table 2 for which it was assumed that  $v_{*r} = (h_r S_r)^{0.5} =$  $h_r L_r^{-0.5}$ . Note that for geometrically similar grains with a similar grain-size distribution, (1 - $\phi)_r = 1$  (Hentschel 2007). Also, for practical purposes, the sediment transport rate is often determined from existing bed load formulae. Using such relationships in equation (18), instead of a measured  $q_*$ , can result in different time scale calculations.

Equation (16) in Table 2 was derived by Yalin (1971) and describes the time scale related
to the evolution of the mobile bed surface in horizontal direction. This equation is based on
26

503 single grain movement considerations and the relation of the diameter scale with the 504 longitudinal scale.

505 Comparing the different time scales given in Table 2 it becomes apparent that

$$506 t_{\eta r} < t_{Lr} < t_r < t_{sgr} (19)$$

507 i.e. the vertical evolution of the bed surface has the shortest time scale, followed by the 508 longitudinal displacement of the grains and the hydrodynamic time scale. The longest time 509 scale is for the individual motion of a grain (Peakall *et al.* 1996). Other time scales than 510 those discussed here may be derived based on the consideration of the evolution of 511 morphodynamic features such as meander bend migration rate, floodplain evolution and 512 biological development (Tal and Paola 2007; Kleinhans *et al.* 2014, and references 513 therein).

The time scales can also be linked to the bed-load models defined above. In *undistorted* similarity models with unidirectional flow  $t_{sg,r} = t_{\eta r} = t_{Lr} = L_r^{0.5}$ , which is equal to the hydraulic time scale  $t_r$ . Geometric similarity models therefore offer the opportunity to study the effects of hydrographs on bed evolution. The time scales for *distorted lightweight models* can be derived as  $t_{sg,r} = (\rho_s - \rho)_r^{-2/3}$ ,  $t_{\eta r} = h_r^3(1-\phi)_r (\rho_s - \rho)_r^{-2/3}$ ,  $t_{Lr} = h_r^2(\rho_s - \rho)_r^{-1}$  thereby assuming  $q_{r^*} = 1$  and that bed shear stress can be determined from the depth slope product.

The time scales for *process-focused models* are defined by equations (14) and (15) where the latter formulation by Tsujimoto (1990) was derived by considering the Manningequation, i.e. by considering additional similarity in bed roughness. Time scales for models with suspended load were summarized by e.g. Hughes (1993) and Van Rijn *et al.* (2011), but in almost all cases a morphological time scale of suspended models was derived corresponding to  $t_{\eta r} = h_r^{0.5}$  (where the vertical length scale characterizes wave characteristics). These similarity conditions can result in rather impractical scaling ratios,

528 especially when considering both vertical and horizontal directions, and result in a 529 challenge in developing strictly scaled models containing both sediment and water.

530

#### 3.2. Representing variable forcing and sequences of events

531 Future climate regimes are anticipated to be characterised by increased variability and higher 532 frequency and magnitude of extreme events such as river flooding (Table 1, Figure 5). Due to the 533 difficulties in scaling unsteady flows and sediment transport in physical models (see section 3.1), 534 there are few physical modelling studies exploring sequences of multiple floods (e.g. Braudrick et 535 al., 2009). In terms of improving our understanding of the impact of climate change on fluvial 536 environments, it would be particularly relevant to investigate variations in hydrograph 537 characteristics (i.e. duration, magnitude and frequency) over time scales that are similar to the 538 system recovery time for morphodynamics and vegetation. All systems have a characteristic time 539 scale for recovery following a perturbation (Brunsden and Thornes 1979). This time scale can range from  $>10^3$  years in erosive bedrock settings (e.g. canyons; Baynes *et al.* 2015) to  $10^1 - 10^2$  years in 540 541 alluvial depositional fluvial environments (e.g. sandur plains; Duller et al. 2014) due to the relative 542 differences in the mobility of sediments, although larger systems typically take longer to fully 543 recover following a perturbation (Paola 2000). This illustrates that the timing of sequences of flood 544 events relative to the time scale of recovery is as important in driving evolution and change in 545 fluvial environments as the magnitude of individual flood events (Figure 5). With an increased 546 frequency of extreme events, this recovery timescale may be threatened, with subsequent events of 547 possibly greater magnitude occurring before the system has fully recovered from the initial 548 perturbation with potentially unknown consequences. Thus, the accurate representation of non-549 constant forcing and the relative importance of sequences of events within physical models remains 550 an important goal for the development of the understanding of fluvial system response to future 551 climate scenarios. Additionally, non-linear threshold driven sediment transport processes which 552 respond to constant or non-constant forcing can destroy or 'shred' environmental signals, like river

553 avulsions or bar deposits, which could otherwise be preserved in the landscape or sedimentary 554 record (Jerolmack and Paola, 2010). Changes in the external forcing may not be preserved if the 555 timing and magnitude of the events does not exceed the autogenic variability driven by non-linear 556 processes such as bedload transport or river avulsion (Jerolmack and Paola, 2010). As the signal of 557 the external forcing increases in frequency (e.g., Fig. 5), preservation of the impact of the individual 558 events becomes less likely, whilst events of sufficiently large magnitude will change or modify the 559 entire system and will therefore have greater potential to be preserved (Jerolmack and Paola, 2010). 560 If the evidence for changes in external forcing are not recorded or visible in natural systems, 561 physical models provide a unique opportunity to understand how thresholds and autogenic 562 feedbacks within a system can mitigate or enhance the impact of variations in external forcing 563 driven by climate change.

564

565 Traditionally, flood events are represented in physical models at the event scale by 566 triangular hydrographs with possibly an asymmetry between the rising and falling stages 567 (e.g Lee et al., 2004 . The gradual increase and decrease of discharge are reproduced by 568 stepped hydrographs with the number of steps for each hydrograph strongly dependent on 569 the complexity of the flume control equipment (Lee et al. 2004; Ahanger et al. 2008). 570 Sequences of flood events modelled on a particular system, or the long-term evolution of a 571 system driven by a long-term shift in the magnitude or frequency of forcing are rarely 572 represented in physical models (Figure 5).



Figure 5. Conceptual diagram indicating different forcing regimes in fluvial and fluvially-affected 574 575 systems such as river deltas and estuaries under climate change. (A) A progressive increase in a 576 constant forcing over a long time scale (e.g. sea level rise, or increase in biostabilisation as a result 577 of temperature increase). (B) A forcing regime characterised by infrequent and low-magnitude 578 extreme events, superimposed on the progressive trend shown in (A). (C) A forcing regime 579 characterised by higher magnitude extreme events, but of the same frequency, compared to (B). 580 (D) A forcing regime characterised by extreme events of the same magnitude as (B), but occurring 581 more frequently. (E) A forcing regime characterised by extreme events that are both more frequent 582 and of a higher magnitude compared to (B). The typical time for the system to recover back to 583 equilibrium conditions is shown in grey in B-E. Due to frequency and magnitude of the extreme 584 events in (E), the system has never fully recovered before the subsequent extreme event, placing 585 the system in a constant state of transience.

587

#### 3.3. Representing biology and timescales of biological change

588 Currently, most hydraulic facilities are not well suited to work with living organisms. These 589 facilities may therefore result in biota being stressed by one or more environmental factors 590 including inappropriate water chemistry (salinity, pH, dissolved oxygen, inorganic carbon), water 591 temperature, substrate (physical and chemical properties, soil saturation), lighting (composition, 592 intensity, timing), and flow characteristics (depth, velocity, drag). The health and behaviour of 593 living plants may also be affected by biological considerations, including insufficient nourishment 30 594 (type, quantity, and timing), competition for resources amongst individuals and, potentially, the 595 introduction of pathogens. Johnson et al., (2014a) provide a review of these main stressors and their 596 management in flume facilities. Of course, plants are often stressed in their natural environment by 597 competition for resources and by other ecological and biological interactions. Their interactions 598 with their environment are variable and complex, such that there is no ideal stress-free state that 599 must be mimicked. Nevertheless, a basic goal of most experimental work will be to reproduce in the 600 flume behaviours that are typical in nature and, in that case, low levels of stress are desirable, or the 601 development of surrogates that accurately replicate plant/microbial activity and can be time scaled.

Most plants are able to tolerate a range of environmental conditions, with fatality beyond limiting thresholds. As conditions become less optimal, but sub-lethal, the plant will adapt, potentially altering the way in which it interacts with the flow. We know very little about these adaptations and what they mean for hydraulic performance, but existing work suggests that the relations are likely to be complex, especially where multiple stressors are present (Puijalon *et al.* 2007).

607 Demonstrating that vegetation is not physiologically or behaviourally stressed during 608 experiments should be a standard element of any physical modelling experiment involving 609 live plants. Without that assurance it is difficult to be confident that measured hydraulic and 610 morphodynamic responses can be properly assigned to treatment effects, not abnormal 611 behaviour caused by the physical modelling environment. While it may be relatively easy 612 to detect serious ill-health or the death of a plant that is part of a flume experiment, earlier 613 stages of decline that affect the plants interaction with the flow, may go undetected, 614 potentially undermining the results obtained.

This leads to the identification of two key challenges for investigating plant-flow-sediment interactions: i) developing protocols that can be used to monitor plant health or stress levels during physical modelling experiments, and ii) developing a fuller understanding of how health and stress levels affect key plant structures, physiological responses and

behaviours that are relevant to flow and sediment interactions. Meeting these challenges would provide a basis for making objective decisions about how stressed a plant is and whether the level of stress is sufficient to affect its biomechanical behaviour as that affects its interactions with the flow and therefore the integrity of an experiment.

623 From a scaling perspective, of primary interest is the role of the hydraulics as a driving 624 force for the growth and, hence, the geometrical and mechanical properties of plants and 625 biofilms. Hydrological modifications, driven by climate change, especially in terms of flood 626 intensity and frequency, are very likely to also modify plant diversity and distribution 627 (Garssen et al. 2015). Importantly, the time scales associated with plant and biofilm growth 628 in the field are very large when compared to the time scales of physical modelling 629 experiments in the laboratory. For photosynthetic biofilms in rivers, for example, growth 630 cycles are associated with time scales of around 30 days, which correlates approximately 631 to inter-flood periods in the field (see e.g. Boulêtreau et al. 2010)). Macrophytes or riparian 632 vegetation generally develop and grow over much longer time scales. For biofilms, another 633 issue is the extreme versatility of this biological agent, whose growth and composition 634 adapts very quickly to flow conditions during growth; for example, Graba et al. (2013) 635 demonstrated that in steady-flow growth experiments the biofilms optimized their 636 mechanical properties to fit the imposed steady forcing, and were very easily detached by 637 a slight increase of flow velocity. Incorporating flow unsteadiness associated with typical 638 discharge fluctuations then becomes important for growing representative laboratory 639 biofilms.

Plants and biofilms can be simplified and represented by some physical or chemical surrogates. As far as plants are concerned, the use of physical surrogates offers the opportunity to better control the interactions between aquatic vegetation and a changing hydraulic environment, without the issue of phenotypic plasticity typical from biotic systems (Read and Stokes 2006; Nikora 2010). However, the development of surrogates relies on 32 the good understanding of the plant biomechanical properties and requires therefore extensive field data collection prior to the main experiments (Nikora 2010). Although recent works are relying more and more on plant surrogates (see Johnson *et al.* (2014b) for a non-exhaustive list), only a few studies investigated the surrogate design process for complex shaped aquatic plants, such as the work carried out by Paul and Henry (2014), and this process is yet to be developed for freshwater aquatic vegetation.

651

# 4. Innovative approaches and required future developments to represent climate change impacts in physical models.

654

## 4.1. Bridging the timescale gap

655 The range of physical modelling approaches highlighted in Figure 2 have worked well for both 656 small and large spatial and temporal scales. At the event scale, 1:1 physical models have proven 657 invaluable tools to examine the effects of storm wave on flooding risk and safety (Figure 3). More 658 extreme storm wave and river flood events are projected as a result of climate change (Table 1). 659 The current hydraulic facilities are however expected to incorporate these more extreme events in 660 their experiments seamlessly by adjusting their test scenarios to include the latest climate 661 projections (e.g., wave height). Other than potentially running into size limitations of the hydraulic 662 facility (i.e. larger events require larger facilities for 1:1 modelling, such as the Mississippi Basin 663 Model; Foster, 1971), these more extreme events do not require additional scaling compared to 664 default extreme event tests. This observation indicates that no problems are foreseen in representing 665 more extreme events associated with climate change in hydraulic facilities.

Also at larger spatial (landscapes) and temporal (>10<sup>2</sup> years) scales, *analogue* models have worked
well leading to agenda-setting research and understanding of landscape evolution processes
(Hasbargen and Paola 2000; Turowski *et al.*, 2006; Tal and Paola 2007; Bonnet 2009). *Analogue*

669 models can act as a tool for exploration, due to the ability to simplify aspects of a complicated 670 system and explore the behaviour of targeted processes under controlled conditions (Bonnet 2009). 671 The freedom given by foregoing the strict scaling laws can potentially allow innovative experiments 672 to develop an understanding of systems that are manipulated in ways that would not be possible 673 using a strict scaling approach, such as coastal dynamics and response to sea-level rise (Kim et al. 674 2006) or the exploration of different sequences of events on the overall system behaviour (e.g., 675 Ganti et al. 2011). It is important to note that analogue models are exclusively fit for these 'thought-676 provoking' experiments and hence our primary tool for investigating processes, interactions and feedbacks across longer (> $10^2$  years) time scales relevant for climate adaptation purposes (Figure 677 678 2).

Intermediate time scales  $(10^1 - 10^2 \text{ years})$  have proven difficult to represent in physical models to 679 680 date, leaving us with a timescale gap in physical modelling capabilities. Yet, in the context of 681 climate change adaptation for planning and policy purposes, the evolution of fluvial systems due to 682 climate change over intermediate time scales is most prevalent and urgent (Figure 2). Depending 683 on the exact timescale or process of interest, undistorted, distorted and process-focused models may 684 provide physical scaling approaches to study the fluvial system at hand. Undistorted and distorted 685 scaled models are best suited to investigate individual and short-lived events due to the minimum 686 compression of spatial and temporal scales (Figure 2extending the individual event scale covered 687 by 1:1 models. Similarly, process-focused and perhaps some distorted and analogue-reach physical 688 models are best placed to condense the timescales represented in analogue models in an effort to 689 study the effects of intermediate timescales of climate change in fluvial systems (OBFORFORF the 690 effects of variable forcing, sequences of events and biological interactions are dominant 691 (Garssen) *et al.* 2015) but poorly understood drivers of fluvial system behaviour. 692 researchers to be able to study the effects of climate change across intermediate timescalesBelow, 693 we provide examples of studies on variable forcing, sequences of events, lightweight sediment and 694 biology and we discuss how they can be applied to better represent climate change at intermediate

timescales specifically and expand the future physical modelling capability more generally.. Below, we provide examples of studies on variable forcing, sequences of events, lightweight sediment and biology and we discuss how they can be applied to better represent climate change at intermediate timescales specifically and expand the future physical modelling capability more generally.. Below, we provide examples of studies on variable forcing, sequences of events, lightweight sediment and biology and we discuss how they can be applied to better represent climate change at intermediate timescales specifically and expand the future physical modelling capability more generally.. Below, we provide examples of studies on variable forcing, sequences of events, lightweight sediment and biology and we discuss how they can be applied to better represent climate change at intermediate timescales specifically and expand the future physical modelling capability more generally.

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703

#### 4.2. Variable forcing and event sequences

704 Recently, Martin and Jerolmack (2013) have advanced the knowledge of bedform 705 dynamics for non-stationary flows, including the difference in the scaling of 706 morphodynamic and hydrodynamic processes (Section 3.1). The processes associated 707 with the growth of bedforms following an abrupt increase in discharge and their decay 708 following an abrupt decrease in discharge are complex and very different (Martin and 709 Jerolmack, 2013). The former relies on gradual collision and merging of small structures towards larger ones, while the latter relies on the formation of secondary small scale 710 711 structures that cannibalize progressively the large structures formed earlier during the 712 rising stage (Martin and Jerolmack 2013). The timescale of the bedform response under 713 these conditions is proportional to the reconstitution time, defined as  $T_r = V/q_s$  where V is the volumetric sediment displacement for the bedform adjustment and  $q_{\text{s}}$  is the sediment 714 715 flux (Martin and Jerolmack, 2013). The reconstitution time is a function of the equilibrium 716 bedform heights, and celerities under the initial and secondary discharge magnitudes, 717 such that taller and longer bedforms take longer to return to equilibrium following an abrupt 718 change in discharge.

719 Additionally, the mechanism and characteristics of the forcing change (i.e., discharge) was 720 found to be important in setting the mechanism of bedform response on the channel bed 721 (Figure 6). Dependent on the rate of a gradual increase and decrease in the discharge 722 (Figure 6a-b), bedforms either respond through a phase of hysteresis or through a linear 723 response of the length and height (Figure 6c-f). Under the 'fast flood wave' conditions, the 724 timescale response of the bedform adjustment is shorter than the timescale of flood wave 725 discharge, forcing the hysteresis response. These observations following their experiments 726 under variable forcing allowed Martin and Jerolmack (2013) to propose a simple model 727 framework for the quantitative prediction of bedform adjustment timescale and the 728 occurrence of bedform hysteresis in natural rivers during individual or sequences of events. 729 This innovative example demonstrates the future potential for physical models in 730 advancing the understanding of the processes and response of fluvial systems under 731 variable forcing conditions, aiding the understanding of the possible impacts of climate 732 change. The identification of response timescales of morphodynamic processes to 733 individual events (i.e., Martin and Jerolmack, 2013) can act as a starting point for 734 evaluating the response to sequences of multiple events of different frequencies and 735 magnitudes (Figure 6).



736

Figure 6. Comparison of bedform dynamics under different variable discharge regimes. (a) Hydrograph simulating a slow flood wave. (b) Hydrograph simulating fast flood wave. (c-d) Evolution of bedform height during the hydrographs. (e-f) Evolution of bedform length during the hydrographs. A clear hysteresis is apparent in the evolution of the bedforms during the fast flood wave, due to time lag of response of the bedforms is greater than the timescales of the flood waves. Adapted from Martin and Jerolmack (2013).

The order of events can also be important for experiments investigating the impact of sequences of events, due to differences in sediment transport rate for flood events of different magnitude and duration. However, the reorganisation of bed morphology either in terms of bedform size or bed structure through events will impact on the state of the system for the next event, which means that the order of events could be significant and this should be addressed in flume experiments that investigate longer time scales.

749

#### 4.3. Lightweight sediments

750 Lightweight materials have been used to study local erosion processes such as scour development downstream of weir structures (e.g., Ettmer, 2006, and references therein), bridge piers and 751 752 abutments (Fael et al. 2006; Ettmer et al. 2015) and the impact of jets (e.g. Rajaratnam and 753 Mazurek 2002). The latter studies, in particular, made use of the fact that erosion processes are 754 accelerated when lightweight sediments are used instead of natural fluvial sediments, i.e. that the 755 equilibrium dimensions of the scour can be reached faster, allowing the time scales of study to be 756 extended (Figure 2). At a larger scale, Willson et al. (2007) reported on a distorted scale 757 model focusing on river and sediment diversions in the lower Mississippi river delta with  $L_r$ = 1:12,000 and  $h_r$  = 1:500 and a model sediment with a density  $\rho_s$  = 1050 kg/m<sup>3</sup> covering 758 77 river miles and an area of about 3526 square miles. In this model, the flow was scaled 759 760 via the Froude law and the lightweight sediment was scaled based on considerations for 761 the incipient motion of the particles so that incipient motion and resuspension were similar 762 in model and prototype. The resultant sediment time scale was given by the authors with 763 1:17.857 (one year of prototype time equals roughly 30 minutes of model time). This model 764 was run for different scenarios, including sea-level rise, and used to enhance the general 765 understanding of the impact of planned measures for US State and Federal Agencies 766 (Willson et al., 2007). Such approaches, specifically using lightweight sediment to reduce 767 the time scale of the environmental processes in the physical models can extend the

timescale of scaled models (Figure 2) to bridge the gap in modelling capabilities over thetimescale relevant for climate change.

770

## 4.4. Representing biology

771 Time scales associated with the growth and behaviour of vegetation are inherently difficult 772 to downscale in physical models using undistorted or distorted models. Therefore, it is 773 more convenient to use living or artificial surrogates within the analogue modelling 774 approach, where the effects of vegetation in the system are replicated, but not necessarily 775 directly. Plant surrogates also offer new possibilities to test hypotheses in the context of 776 changing fluvial systems. Johnson et al., (2014b) detailed the various benefits and the 777 limitations of using inert physical surrogates, and these points will therefore not be detailed here. Yet, surrogate development is still in its infancy and depends on a detailed 778 779 knowledge of the morphology and biomechanics of the species of interest, and we present 780 here some of the major issues yet to be tackled, in the context of changing fluvial systems.

781 The morphology and mechanics of aquatic plants can vary based on seasonal patterns. In 782 flume experiments, the potential interaction between the different time scales such as the 783 seasonal growth and the time between active and inactive hydrological regimes needs to 784 be considered. In the case of experiments involving time compression (analogue or 785 process-focused models always active/in flood, see e.g. Paola 2000) effects due to 786 seasonal changes of plant characteristics may be lost. A good understanding of the plant 787 biomechanical properties requires the use of a solid dataset from real-life conditions 788 (Nikora 2010), collected using well identified techniques (Henry 2014; 2018). Additionally, 789 the required level of complexity of a plant surrogate is still uncertain, as it is critical not to 790 simply redesign the plant structure (Denny 1988). Understanding the existing structural 791 organisation of a plant is key to the identification of the environmental factor that defined it, 792 and should highlight the features to be reproduced in an experiment, depending on the

793 processes and scales to be investigated. The most important part in a design process, i.e. 794 performance tests, should be conducted systematically to ensure that the dynamic 795 behaviours of the surrogate correspond to the original criteria, i.e. the reproduction of the 796 process observed in nature (flexibility, plant to plant interaction, effect on sediment 797 transport).

798 The application of models without scaling to address guestions relating to climate change 799 has some limitations because model time is no faster than prototype time, but for 800 understanding some interactions between organisms and their surroundings, there are no 801 satisfactory scaling relationships (e.g. Wilcock et al. 2008). Kui et al. (2014) present results 802 from the StreamLab experiments that are used to elucidate the eco-geomorphic feedbacks 803 between riparian tree seedlings and flood events. These 1:1 physical models investigate 804 the use of flood releases to control invasive vegetation, however this type of model has the 805 potential to improve our understanding of the response of trees and other organisms to 806 extreme events that could be associated with climate change.

807 In theory, it is possible to scale down plant properties within the distorted scale modelling 808 approach, which may lead to a distortion in time and/or space of the hydraulic model (Johnson et al. 2014b). In practice, no such work has been published to the best of our 809 810 knowledge, and investigations related to scaled plant properties are just about to start. The 811 interaction of this new distorted 'plant time scale' with the other time scales applying to 812 sediment transport and larger morphological evolutions, is yet to be characterised but 813 offers a potentially important avenue for future work into the holistic evolution of river 814 systems under climate change forcing.

For plants, several studies have relied on the use of *alfalfa* because of its size and growth time scale fit with a downscaling approach to physical modelling of sediment and flow dynamics and their interactions with vegetation. This analogue modelling approach leads

818 to floodplains vegetated by a single species that resembles a very fast growing tree 819 (Figure 7). Vegetation is able to stabilise river banks, focus and organise the flow and hence 820 convert the planform morphology from braided to single-thread (Gran and Paola 2001; Tal et al. 821 2004; Tal and Paola 2007, 2010; Braudrick et al. 2009; Van de Lageweg et al. 2010; Van Dijk et al. 822 2013; Bertoldi *et al.* 2014). It should be noted, however, that vegetation alone does not lead to fully 823 meandering channels (Desloges and Church, 1989) and fine grained material is also required (Van 824 Dijk et al. 2013; Santos et al., 2017a,b). Morphological trends associated with the colonisation of a 825 floodplain by riparian vegetation are an increased sinuosity, lower lateral migration rates, a reduced 826 number of channels, deepening of the channels, and a reduction in the wetted area, and potentially 827 can provide insights into the large-scale evolution of river systems under climate-induced variability 828 into vegetation patterns.



829

830 Figure 7. Example of a physical model in which the original fluvial braided plain has been colonised 831 by small-scale alfalfa vegetation. Flow is from right to left and the panel is 6 m long and 2 m wide. 832 In addition to plant surrogates, it may be possible to use chemical surrogates to simulate 833 aspects of biofilm mediated stabilization processes. Xanthan gum (a rheology modifier 834 often used in the food industry) is one example of such a surrogate and has been 835 employed in a number of studies to mimic natural biofilm behaviour (Black et al. 2001; 836 Tolhurst et al. 2002). Even though it has been demonstrated that Xanthan gum is not a 837 perfect analogue of natural biofilms (Perkins et al. 2004), primarily because natural 838 biofilms are more complex, it is seemingly useful in studies on sediment erosion, with 839 increasing quantities of Xanthan gum having a clear effect on the morphology of bedforms 840 (Malarkey et al., 2015; Schindler et al., 2015; Parsons et al., 2016; Figure 8Figure 8Figure 41

841 8<sup>cool</sup>Figure 8<sup>cool</sup>)<sup>cool</sup>. A recent experimental investigation compared the stabilisation effects 842 for sand of Xantham Gum to three other chemical surrogates; Alginic Acid, Carrageenan 843 and Agar (van de Lageweg *et al.* 2018). Alginic Acid and Agar had a limited effect, as the 844 erosion threshold for the sediment did not increase while the erosion threshold increased 845 linearly for increased concentrations of Xantham Gum and Carrageenan (van de Lageweg 846 *et al.*, 2018), potentially providing a method of speeding up time scales of physical 847 modelling experiments investigating biostabilization effects.



Figure 8. Effect of extracted extracellular polymeric substances (EPS) content on bedform
morphology. (a) 0% EPS, (b) 0.125% EPS content, (c) 1% EPS content. (d) Ripple height
development for different EPS contents (black: 0%, red: 0.016%, green: 0.031%, blue: 0.063%,
pink: 0.125%). Adapted from Malarkey *et al.*, (2015).

853

848

#### 854 4.5. Infrastructural developments

A potential barrier preventing the implementation of the innovative approaches discussed above arethe physical limitations of the infrastructure associated with the available physical modelling

857 facilities. An obvious example, given the potential stresses placed on growing plants and vegetation 858 in the unnatural conditions of many physical modelling laboratories, is improved facilities designed 859 for optimal biological growth. Potential developments include climate and light-controlled 860 conditions, nutrient delivery, and stress monitoring protocols during the set up and duration of 861 experiments (Johnson et al., 2014a). An additional infrastructural development that is required 862 relates to the measurement and monitoring techniques employed during physical modelling 863 experiments. Especially as the understanding of the impact of climate change and variable forcing 864 in fluvial systems requires a quantification of both short-term and longer-term dynamics (e.g. the 865 impact of single storm events on top of the longer term impact of gradual sea-level rise). 866 Monitoring and measuring remains a challenge for studies that aim to quantify and disentangle the 867 impact from individual short-lived events to longer-term trends due to the lack of high resolution 868 monitoring and quantification techniques that can operate over multiple time scales (Kim et al. 869 2006). It is recommended that future studies investigate deltaic and estuarine environments with combined fluvial and tidal currents, and the Metronome tidal facility at the University of Utrecht is 870 871 an innovative facility that has been developed in recent years (Kleinhans et al. 2017). These 872 experiments could provide the ability to observe, monitor and characterise the driving processes that 873 lead to the transition between different equilibrium conditions, and the balance of different aspects 874 of the fluvial landscapes and ecosystems in tidally-dominated environments. This would also 875 improve the parameterisation of such processes in numerical models and associated predictions of 876 how fluvial systems may respond to variations in climatic forcing.

877

#### 4.6. Linkages with numerical simulations

878 It is anticipated that combining physical modelling and numerical modelling has the potential to be 879 a robust way forward to address the current gap in the capability to model climate change 880 adaptation. For example, physical modelling can be used to perform focussed sensitivity analyses 881 on the impact of individual parameters in controlled environments, aiding the parameterisation of 882 numerical models that simulate processes such as flow-vegetation interactions (Marjoribanks *et al.* 43 883 2015). Numerical models parameterised from empirical data have explored scenarios and provided 884 projections for the evolution of fluvial landscapes (Coulthard et al., 2007; Nicholas and Quine 2007; 885 Attal et al. 2008; Nicholas 2013; Edmonds and Slingerland 2010; Schuurman et al. 2013; Liang et 886 al. 2016), sediment-vegetation interactions in these systems (van Oorschot et al. 2016), and the 887 evolution of coastal barrier systems (Castelle et al., 2013). Using datasets from the Barrier 888 Dynamics Experiment (BARDEX II; Masselink et al. 2013), allowed the testing of existing 889 numerical models and to identify priorities for their existing development in order to 890 reproduce processes such as onshore/offshore sandbar migration (1DBeach model; 891 Castelle et al. 2010), barrier erosion sequences (XBeach model; Roelvink et al. 2009) and the impacts of overtopping (SURF\_GN model; Bonneton et al. 2011). Testing of numerical 892 893 models against physical modelling datasets could increase the confidence in numerical 894 simulations, improving the capability to model climate change adaptation. It may be noted 895 that the development of the use of inert plant surrogates may also help and be done in parallel to numerical modelling studies replicating fluid flow around vegetation 896 897 (Marjoribanks et al. 2014; 2015), whose effects can be included into larger numerical 898 simulation addressing fluvial adaptation at a larger space and time scale.

899 Numerical models can be used to explore which combinations of variables are most worth studying 900 in physical experiments and can aid with the planning of such experiments. Once accurately 901 parameterised and calibrated in physical models, process-based numerical models could be upscaled 902 to cover larger spatial scales and longer time periods that are appropriate for climate change 903 adaptation (i.e. intermediate scales). Also, numerical model simulations can be useful predictive 904 tools because they can cover multiple spatial and temporal scales and they can easily be forced with 905 a multitude of climate change scenarios that would be impractical using physical models. However, 906 these numerical simulations often contain associated uncertainty due to the inability to determine 907 whether the observed behaviour is a result of true landscape dynamics or merely an artefact of the 908 model set up. Physical models could potentially improve this confidence by replicating some of the

same scenarios and comparing the behaviour and interactions between processes in both thenumerical and physical simulations.

911

#### 912 **5. Conclusions**

913 Physical modelling has contributed significantly to our understanding of fluvial systems. This is 914 expected to continue into the future as different physical modelling approaches are well suited to 915 investigate the response and potential adaptation to climatically driven changes in forcing over 916 various timescales. Based on a review of the state-of-the-art in physical modelling of fluvial 917 systems, this study highlights that: (i) physical modelling offers a prime opportunity for furthering 918 the current understanding of variability of forcing in fluvial systems. (ii) For the policy focused 919 studies of fluvial systems undergoing climate change adaptation, the modelled time scales using 1:1, 920 undistorted or distorted scale models need to be extended and the modelled time scales using 921 process-focused or analogue models need to be reduced to address issues relevant to decadal 922 timescales. (iii) Representing the response of plants and organisms to changing conditions and the 923 resulting feedback on physical processes requires more attention and better techniques than 924 presently available, using both *distorted scale* and *analogue* surrogate modelling approaches. (iv) 925 Coupling of physical modelling output with numerical model parameterisation and development is 926 crucial for producing accurate predictions of how fluvial systems will respond in the future to a 927 range of possible forcing scenarios over multiple time scales.

Within the context of climatic change in fluvial environments, future focus and investment is recommended towards the physical modelling of the detailed interactions between riverine biology, hydrology and morphology, non-constant forcing and an understanding of the impacts of single events, multi-decadal oscillations and longer term trends. This will enable the development of appropriate and effective mitigation strategies for fluvial ecosystems and environments under threat from climate change, that are grounded in robust physical experimentation.

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