

# Classification of integrable (2+1)-dimensional quasilinear hierarchies

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**ABSTRACT.** We investigate (2+1)-dimensional hierarchies associated with integrable PDE's of the form

$$\Omega_{tt} = F(\Omega_{xx}, \Omega_{xt}, \Omega_{xy}),$$

which generalize the dispersionless KP hierarchy. The integrability is understood as the existence of infinitely many hydrodynamic reductions.

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## 1. Introduction

Let us consider a function  $\Omega$  of infinitely many independent variables  $t^0, t^1, t^2, \dots$  satisfying a system of second order PDE's

$$\Omega_{nk} = \Phi_{nk}(\Omega_{00}, \Omega_{01}, \Omega_{02}, \dots, \Omega_{0,n+k});$$

here  $\Omega_{nk} \equiv \partial_{t^n} \partial_{t^k} \Omega$ ,  $n \geq 1, k \geq 1$ . Explicitly, one has

$$\begin{aligned} \Omega_{11} &= \Phi_{11}(\Omega_{00}, \Omega_{01}, \Omega_{02}), \\ \Omega_{12} &= \Phi_{12}(\Omega_{00}, \Omega_{01}, \Omega_{02}, \Omega_{03}), \\ \Omega_{13} &= \Phi_{13}(\Omega_{00}, \Omega_{01}, \Omega_{02}, \Omega_{03}, \Omega_{04}), \\ \Omega_{22} &= \Phi_{22}(\Omega_{00}, \Omega_{01}, \Omega_{02}, \Omega_{03}, \Omega_{04}), \end{aligned} \tag{1}$$

etc. Equations of this type generalize the dispersionless KP hierarchy

$$\begin{aligned} \Omega_{11} &= \Omega_{02} - \frac{1}{2}\Omega_{00}^2, \\ \Omega_{12} &= \Omega_{03} - \Omega_{00}\Omega_{01}, \\ \Omega_{13} &= \Omega_{04} - \Omega_{00}\Omega_{02} - \frac{1}{2}\Omega_{01}^2, \\ \Omega_{22} &= \Omega_{04} + \frac{1}{3}\Omega_{00}^3 - \Omega_{00}\Omega_{02} - \Omega_{01}^2, \end{aligned}$$

etc. Further examples arise in the theory of Dirichlet's problem in multi-connected domains [8]. The compatibility conditions of the equations (1) impose strong restrictions on the functions  $\Phi_{nk}$  implying, in particular, that  $\Phi_{11}$  uniquely determines the rest of the functions  $\Phi_{nk}$  [10], [2]. The function  $\Phi_{11}$  itself satisfies a complicated over-determined system of third order PDE's (see Sect. 2 where we re-derive this system based on the method of hydrodynamic reductions [7], [4], [6], [9]). Its general solution can be reduced to either of the four essentially different canonical forms

$$\begin{aligned} \Phi_{11} &= \Omega_{02} + \frac{1}{4A}(A\Omega_{01} + 2B\Omega_{00})^2 + Ce^{-A\Omega_{00}}, \\ \Phi_{11} &= \frac{\Omega_{02}}{\Omega_{00}} + \left( \frac{1}{\Omega_{00}} + \frac{A}{4\Omega_{00}^2} \right) \Omega_{01}^2 + \frac{B}{\Omega_{00}^2} \Omega_{01} + \frac{B^2}{A\Omega_{00}^2} + Ce^{A/\Omega_{00}}, \\ \Phi_{11} &= \frac{\Omega_{02}}{\Omega_{01}} + \frac{1}{6}\eta(\Omega_{00})\Omega_{01}^2, \\ \Phi_{11} &= \ln \Omega_{02} - \ln \theta_1(\Omega_{01}, \Omega_{00}) - \frac{1}{4} \int_{\Omega_{00}}^{\Omega_{01}} \eta(\tau) d\tau, \end{aligned}$$

see [10]. Here  $\eta(\tau)$  is a solution of the Chazy equation

$$\eta''' + 2\eta\eta'' = 3\eta'^2, \tag{2}$$

which can be represented in parametric form

$$\eta(\tau) = \frac{4}{\pi^2} \mathbf{K}(s) [(2 - s^2) \mathbf{K}(s) - 3\mathbf{E}(s)], \quad \tau = -\pi^2 \frac{\mathbf{K}(\sqrt{1 - s^2})}{\mathbf{K}(s)},$$

where  $\mathbf{K}(s)$  and  $\mathbf{E}(s)$  are complete elliptic integrals of the first and second kind, respectively [1]. The theta-function

$$\theta_1(z, \tau) = 2 \sum_{n=0}^{\infty} (-1)^n e^{-(n+1/2)^2 \tau} \sin[(2n+1)z]$$

is defined as a solution of the involutive system

$$\begin{aligned} \partial_z \theta_1 &= -k \theta_1, \quad \partial_\tau \theta_1 = \frac{1}{4}(k^2 - l) \theta_1, \\ \partial_z k &= l, \quad \partial_\tau k = \frac{1}{4} \sqrt{4l^3 - 4\eta l^2 - 8\eta' l - \frac{8}{3}\eta''} - \frac{1}{2} k l, \end{aligned} \quad (3)$$

$$\partial_z l = \sqrt{4l^3 - 4\eta l^2 - 8\eta' l - \frac{8}{3}\eta''}, \quad \partial_\tau l = l^2 - \eta l - \eta' - \frac{1}{2} k \sqrt{4l^3 - 4\eta l^2 - 8\eta' l - \frac{8}{3}\eta''},$$

where, again,  $\eta$  solves the Chazy equation (2). We emphasize, however, that one does not need the explicit formulae for  $\theta_1$  and  $\eta$  to work with the above expressions for  $\Phi_{11}$ : what one actually needs are the equations (2), (3).

The dKP hierarchy corresponds to a simple degeneration of the first canonical form:  $A = -2B^2$ ,  $B \rightarrow 0$ ,  $C = 0$ . Similarly, the hierarchy of the modified dKP equation,

$$\Omega_{11} = \Omega_{02} + B\Omega_{00}\Omega_{01} + \frac{B^2}{3}\Omega_{00}^3,$$

can be obtained by the degeneration  $C = -2B^2 A^{-3}$ ,  $A \rightarrow 0$  (along with an appropriate linear change of the variable  $t^2$ ).

In Sect. 2 we concentrate on the first equation

$$\Omega_{11} = \Phi_{11}(\Omega_{00}, \Omega_{01}, \Omega_{02}), \quad (4)$$

dropping any assumptions on the structure of higher flows of the hierarchy. Introducing the notation  $t^0 \equiv x$ ,  $t^1 \equiv t$ ,  $t^2 \equiv y$ ,  $\Phi_{11} \equiv G$ ,  $\Omega_{00} \equiv a$ ,  $\Omega_{01} \equiv b$ ,  $\Omega_{02} \equiv c$  we rewrite (4) in a quasilinear form

$$a_t = b_x, \quad a_y = c_x, \quad b_y = c_t, \quad b_t = G(a, b, c)_x. \quad (5)$$

Applying to (5) the method of hydrodynamic reductions (as outlined in [6]), we arrive at the same system of PDE's for  $\Phi_{11}$  as the one obtained in [10]. This confirms that the symmetry approach of [10] based on equations (1) yields a *complete list* of integrable PDE's of the form (4).

In Sect. 3 we discuss scalar pseudopotentials

$$\psi_t = Q(\psi_x, \Omega_{00}, \Omega_{01}), \quad \psi_y = L(\psi_x, \Omega_{00}, \Omega_{01}, \Omega_{02})$$

which play a role of dispersionless Lax pairs [12] for equations (4). To calculate pseudopotentials we introduce *negative* times  $t^{-1}$ ,  $t^{-2}$ , ... and consider the corresponding *negative* flows of the hierarchy.

## 2. Classification of integrable PDEs of the form $\Omega_{tt} = G(\Omega_{xx}, \Omega_{xt}, \Omega_{xy})$

In this section we demonstrate how the classification results of [10] (see also [2]) follow from the method of hydrodynamic reductions as proposed in [6]. Introducing the notation  $\Omega_{xx} = a$ ,  $\Omega_{xt} = b$ ,  $\Omega_{xy} = c$ ,  $\Omega_{tt} = G(a, b, c)$  we first rewrite our PDE in the quasilinear

form (5). Looking for hydrodynamic reductions in the form  $a = a(R^1, \dots, R^n)$ ,  $b = b(R^1, \dots, R^n)$ ,  $c = c(R^1, \dots, R^n)$  where the Riemann invariants satisfy the equations

$$R_t^i = \lambda^i(R) R_x^i, \quad R_y^i = \mu^i(R) R_x^i \quad (6)$$

and substituting into (5), one arrives at

$$\partial_i b = \lambda^i \partial_i a, \quad \partial_i c = \mu^i \partial_i a$$

along with the dispersion relation

$$(\lambda^i)^2 = G_a + G_b \lambda^i + G_c \mu^i.$$

The commutativity conditions of the flows (6) are of the form

$$\frac{\partial_j \lambda^i}{\lambda^j - \lambda^i} = \frac{\partial_j \mu^i}{\mu^j - \mu^i}, \quad i \neq j, \quad \partial_j = \partial / \partial R^j, \quad (7)$$

see [11]. Differentiating the dispersion relation and taking into account (7) one obtains the expressions for  $\partial_j \lambda^i$  in the form

$$\begin{aligned} \partial_j \lambda^i &= \frac{\partial_j a}{G_c(\lambda^i - \lambda^j)} (G_{aa} G_c + G_{ab} G_c (\lambda^i + \lambda^j) + G_{bb} G_c \lambda^i \lambda^j + \\ &\quad (G_{ac} + \lambda^i G_{bc}) ((\lambda^j)^2 - G_b \lambda^j - G_a)) \\ &\quad + ((\lambda^i)^2 - G_b \lambda^i - G_a) [G_{ac} + G_{bc} \lambda^j + \frac{G_{cc}}{G_c} ((\lambda^j)^2 - G_b \lambda^j - G_a)]. \end{aligned} \quad (8)$$

The compatibility conditions of the equations  $\partial_i b = \lambda^i \partial_i a$  and  $\partial_i c = \mu^i \partial_i a$  imply

$$\partial_i \partial_j a = \frac{\partial_j \lambda^i}{\lambda^j - \lambda^i} \partial_i a + \frac{\partial_i \lambda^j}{\lambda^i - \lambda^j} \partial_j a. \quad (9)$$

One can see that the consistency conditions of the equations (8), that is,  $\partial_k \partial_j \lambda^i - \partial_j \partial_k \lambda^i = 0$ , are of the form  $P \partial_j a \partial_k a = 0$  where  $P$  is a complicated rational expression in  $\lambda^i, \lambda^j, \lambda^k$  whose coefficients depend on partial derivatives of  $G(a, b, c)$  up to third order (to obtain the integrability conditions it suffices to consider 3-component reductions setting  $i = 1, j = 2, k = 3$ ). Requiring that  $P$  vanishes identically we obtain the expressions for all third order partial derivatives of  $G$ . Similarly, the compatibility conditions of the equations (9), that is,  $\partial_k (\partial_i \partial_j a) - \partial_j (\partial_i \partial_k a) = 0$ , take the form  $S \partial_i a \partial_j a \partial_k a = 0$  where, again,  $S$  is rational in  $\lambda^i, \lambda^j, \lambda^k$ . Equating  $S$  to zero one obtains exactly the same conditions as the ones obtained on the previous step. The resulting set of integrability conditions looks as follows:

$$\begin{aligned}
G_{ccc} &= \frac{2G_{cc}^2}{G_c}, & G_{acc} &= \frac{2G_{ac}G_{cc}}{G_c}, & G_{bcc} &= \frac{2G_{bc}G_{cc}}{G_c}, \\
G_{aac} &= \frac{2G_{ac}^2}{G_c}, & G_{abc} &= \frac{2G_{ac}G_{bc}}{G_c}, & G_{bbc} &= \frac{2G_{bc}^2}{G_c}, \\
G_{bbb} &= \frac{2}{G_c^2} (G_b G_{bc}^2 + G_{bc}(G_c G_{bb} + 2G_{ac}) - G_{cc}(G_b G_{bb} + 2G_{ab})), \\
G_{abb} &= \frac{2}{G_c^2} (G_a G_{bc}^2 + G_{ac}(G_c G_{bb} + G_{ac}) - G_{cc}(G_a G_{bb} + G_{aa})), \\
G_{aab} &= \frac{2}{G_c^2} (G_{cc}(G_b G_{aa} - 2G_a G_{ab}) - G_{ac}(G_b G_{ac} - 2G_c G_{ab}) - G_{bc}(G_c G_{aa} - 2G_a G_{ac})), \\
G_{aaa} &= \frac{2}{G_c^2} ((G_a + G_b^2)G_{ac}^2 + G_a^2 G_{bc}^2 + G_c^2(G_{ab}^2 - G_{aa}G_{bb}) \\
&\quad + G_{ac}G_c(G_{aa} + 2(G_a G_{bb} - G_b G_{ab})) + 2G_{bc}(G_b(G_c G_{aa} - G_a G_{ac}) - G_a G_c G_{ab}) \\
&\quad - G_{cc}((G_a + G_b^2)G_{aa} - 2G_a G_b G_{ab})).
\end{aligned} \tag{10}$$

This system is in involution and its general solution depends on 10 integration constants (indeed, the values of  $G$  and its partial derivatives up to second order can be prescribed arbitrarily at any point  $a_0, b_0, c_0$ ).

The integration of the first six equations in (10) yields

$$G(a, b, c) = \frac{1}{\varepsilon} \ln(\alpha a + \beta b + \gamma + \varepsilon c) + F(a, b).$$

The substitution of this ansatz into the remaining equations imposes further constraints on the function  $F(a, b)$ ,

$$\begin{aligned}
F_{bbb} - 4\varepsilon F_{ab} - 2\varepsilon F_b F_{bb} &= 0, \\
F_{abb} - 2\varepsilon F_{aa} - 2\varepsilon F_a F_{bb} &= 0, \\
F_{aab} + 2\varepsilon F_b F_{aa} - 4\varepsilon F_a F_{ab} &= 0, \\
F_{aaa} - 2\varepsilon F_a F_{aa} + 2F_{aa} F_{bb} - 2\varepsilon F_b^2 F_{aa} - 2F_{ab}^2 + 4\varepsilon F_a F_b F_{ab} - 2\varepsilon F_a^2 F_{bb} &= 0,
\end{aligned} \tag{11}$$

which identically coincide with the ones derived in [10]. The first equation in (11) has the general solution

$$F = -\frac{1}{4\varepsilon} \int \eta(a) da - \frac{1}{\varepsilon} \ln \theta(a, b), \quad 4\varepsilon \theta_a = \theta_{bb}, \tag{12}$$

and the substitution of (12) into the remaining equations (11) and further integration lead to the four essentially different cases as shown in [10].

This confirms that the method of higher symmetries adopted in [10] gives *all* integrable hierarchies of the form (1).

### 3. Pseudopotentials

Let us introduce the *negative* times  $t^{-1}, t^{-2}, t^{-3}, \dots$  and extend the hierarchy (1) by the equations

$$\begin{aligned}
\Omega_{n,-k} &= \Phi_{n,-k}(\Omega_{0,-k}, \Omega_{0,-k+1}, \dots, \Omega_{00}, \Omega_{01}, \dots, \Omega_{0n}), \\
\Omega_{-n,-k} &= \Phi_{-n,-k}(\Omega_{0,-n-k}, \Omega_{0,-n-k+1}, \dots, \Omega_{00});
\end{aligned}$$

in particular,

$$\begin{aligned}\Omega_{1,-1} &= \Phi_{1,-1}(\Omega_{0,-1}, \Omega_{00}, \Omega_{01}), \\ \Omega_{2,-1} &= \Phi_{2,-1}(\Omega_{0,-1}, \Omega_{00}, \Omega_{01}, \Omega_{02}).\end{aligned}$$

In the notation  $t^0 \equiv x$ ,  $t^1 \equiv t$ ,  $t^2 \equiv y$ ,  $t^{-1} \equiv z$ ,  $\Phi_{1,-1} \equiv Q$ ,  $\Phi_{2,-1} \equiv L$  we can rewrite these equations in the form

$$\begin{aligned}\Omega_{tz} &= Q(\Omega_{xz}, \Omega_{xx}, \Omega_{xt}), \\ \Omega_{yz} &= L(\Omega_{xz}, \Omega_{xx}, \Omega_{xt}, \Omega_{xy}).\end{aligned}$$

In terms of  $\psi = \Omega_z$  this provides a pseudopotential

$$\begin{aligned}\psi_t &= Q(\psi_x, \Omega_{xx}, \Omega_{xt}), \\ \psi_y &= L(\psi_x, \Omega_{xx}, \Omega_{xt}, \Omega_{xy})\end{aligned}$$

for the equation (4). Below we demonstrate how one can obtain explicit expressions for both functions  $Q$  and  $L$ .

**Remark:** The hierarchy of the Boyer-Finley equation [3]

$$\Omega_{1,-1} = \exp \Omega_{00}$$

can be obtained by a simple degeneration  $B = C = 0$ ,  $A = -2$  in the first canonical form; the first commuting flow of this hierarchy is

$$\Omega_{11} = \Omega_{02} - \frac{1}{2}\Omega_{01}^2.$$

Let us first derive the explicit form for the function  $Q$  applying the method of hydrodynamic reductions to the PDE

$$\Omega_{zt} = Q(\Omega_{xz}, \Omega_{xx}, \Omega_{xt}).$$

Introducing the notation  $\Omega_{xx} = a$ ,  $\Omega_{xt} = b$ ,  $\Omega_{xz} = e$ ,  $\Omega_{zt} = Q(e, a, b)$ , one can rewrite this PDE in the quasilinear form

$$a_t = b_x, \quad a_z = e_x, \quad b_z = e_t = Q(e, a, b)_x. \quad (13)$$

Looking for reductions in the form  $a = a(R^1, \dots, R^n)$ ,  $b = b(R^1, \dots, R^n)$ ,  $e = e(R^1, \dots, R^n)$  where the Riemann invariants satisfy the equations

$$R_t^i = \lambda^i(R) R_x^i, \quad R_z^i = \zeta^i(R) R_x^i$$

and substituting into (13), one arrives at

$$\partial_i b = \lambda^i \partial_i a, \quad \partial_i e = \zeta^i \partial_i a$$

along with the dispersion relation

$$\zeta^i \lambda^i = Q_a + Q_b \lambda^i + Q_e \zeta^i.$$

As before, the commutativity conditions (7) lead to the expressions for  $\partial_j \lambda^i$ , ( $i \neq j$ ), and the compatibility conditions of the equations  $\partial_i b = \lambda^i \partial_i a$ ,  $\partial_i e = \zeta^i \partial_i a$  yield (9). The consistency conditions  $\partial_k \partial_j \lambda^i - \partial_j \partial_k \lambda^i = 0$  are of the form  $R \partial_j a \partial_k a = 0$  where  $R$  is a rational expression in  $\lambda^i, \lambda^j, \lambda^k$  whose coefficients depend on partial derivatives of  $Q(e, a, b)$  up to the third order. Requiring that  $R$  vanishes identically we obtain the expressions for all third order partial derivatives of  $Q$ . Similarly, the compatibility conditions of the equations (9), that is,  $\partial_k(\partial_i \partial_j a) - \partial_j(\partial_i \partial_k a) = 0$ , take the form  $M \partial_i a \partial_j a \partial_k a = 0$  where,

again,  $M$  is a rational expression in  $\lambda^i, \lambda^j, \lambda^k$ . Equating  $M$  to zero one obtains exactly the same conditions as on the previous step. The final set of integrability conditions looks as follows:

$$\begin{aligned}
Q_{bbb} &= \frac{Q_{bb}(Q_b Q_{be} + Q_e Q_{bb} + Q_{ab})}{Q_b Q_e + Q_a}, & Q_{eee} &= \frac{Q_{ee}(Q_{ee} Q_b + Q_e Q_{be} + Q_{ae})}{Q_b Q_e + Q_a}, \\
Q_{bbe} &= \frac{Q_{bb}(Q_{ee} Q_b + Q_e Q_{be} + Q_{ae})}{Q_b Q_e + Q_a}, & Q_{bee} &= \frac{Q_{ee}(Q_b Q_{be} + Q_e Q_{bb} + Q_{ab})}{Q_b Q_e + Q_a}, \\
Q_{aee} &= \frac{Q_{ee}(Q_b Q_{ae} + Q_e Q_{ab} + Q_{aa})}{Q_b Q_e + Q_a}, & Q_{abb} &= \frac{Q_{bb}(Q_b Q_{ae} + Q_e Q_{ab} + Q_{aa})}{Q_b Q_e + Q_a}, \\
Q_{aab} &= \frac{Q_{ab}(2Q_e Q_{ab} + Q_{aa}) + Q_{bb}(2Q_a Q_{ae} - Q_e Q_{aa}) - Q_{be}(2Q_a Q_{ab} - Q_b Q_{aa})}{Q_b Q_e + Q_a}, \\
Q_{abe} &= \frac{Q_{ae} Q_{ab} + Q_a(Q_{bb} Q_{ee} - Q_{be}^2) + Q_{be}(Q_b Q_{ae} + Q_e Q_{ab})}{Q_b Q_e + Q_a}, \\
Q_{aae} &= \frac{2Q_a Q_{ab} Q_{ee} + Q_{aa} Q_{ae} + Q_{be}(Q_e Q_{aa} - 2Q_a Q_{ae}) + Q_b(2Q_{ae}^2 - Q_{aa} Q_{ee})}{Q_b Q_e + Q_a}, \\
Q_{aaa} &= (Q_{aa}[2(Q_b^2 Q_{ee} + Q_e^2 Q_{bb}) + Q_b Q_{ae} + Q_e Q_{ab} + Q_{aa} - 2Q_{be}(Q_a + 2Q_b Q_e)] \\
&\quad + 2Q_{ab}[Q_a(Q_{ae} + 2Q_e Q_{be}) + 2Q_b(Q_e Q_{ae} - Q_a Q_{ee}) - Q_e^2 Q_{ab}] \\
&\quad + 2Q_{ae}[Q_a(2Q_b Q_{be} - 2Q_e Q_{bb}) - Q_b^2 Q_{ae}] + 2Q_a^2[Q_{bb} Q_{ee} - Q_{be}^2]) / (Q_b Q_e + Q_a).
\end{aligned} \tag{14}$$

This system is in involution and its general solution depends on 10 integration constants.

It is easy to see that the general solution of the first six equations is

$$Q = \frac{1}{4} \ln \frac{U(a, p)}{V(a, q)}, \quad 4U_a = U_{pp}, \quad 4V_a = V_{qq},$$

where

$$p = b - e, \quad q = b + e.$$

The general solution of the system (14) can be obtained by the substitution of this ansatz into the remaining equations. Let us introduce the notation

$$Q_p = -\frac{1}{4}k, \quad Q_{pp} = -\frac{1}{4}l, \quad Q_q = \frac{1}{4}m, \quad Q_{qq} = \frac{1}{4}n,$$

here  $\partial_b = \partial_q + \partial_p$ ,  $\partial_e = \partial_q - \partial_p$ . Then the equation (14)<sub>8</sub> takes the form

$$4nn_a - n_q(n_q - 2mn) + 2n[2l_a + kl_p - 2l^2] = 4ll_a - l_p(l_p - 2kl) + 2l[2n_a + mn_q - 2n^2] \tag{15}$$

where

$$\begin{aligned}
Q_a &= \frac{1}{16}[-l + n + k^2 - m^2], & Q_{be} &= \frac{1}{4}(n + l), & Q_b &= \frac{1}{4}(m - k), \\
Q_e &= \frac{1}{4}(m + k), & Q_{bb} &= \frac{1}{4}(n - l), & Q_{ee} &= \frac{1}{4}(n - l), \\
Q_{ae} &= \frac{1}{16}[n_q - 2mn + l_p - 2kl], & Q_{ab} &= \frac{1}{16}[n_q - 2mn - l_p + 2kl].
\end{aligned} \tag{16}$$

The differentiation of (15) twice with respect to  $p$  and  $q$  implies

$$n_q[2l_a + kl_p - 2l^2]_p = l_p[2n_a + mn_q - 2n^2]_q.$$

Assuming that  $n_q \neq 0$  and  $l_p \neq 0$  one obtains

$$l_a = l^2 - \frac{1}{2}kl_p - \eta(a)l - C(a), \quad n_a = n^2 - \frac{1}{2}mn_q - \eta(a)n - B(a),$$

where  $\eta(a)$ ,  $B(a)$  and  $C(a)$  are functions to be determined. Substituting  $n_a$  and  $l_a$  into (15) one has

$$l_p^2 = 4l^3 - 4\eta(a)l^2 - 4[B(a) + C(a)]l - E(a), \quad n_q^2 = 4n^3 - 4\eta(a)n^2 - 4[B(a) + C(a)]n - E(a),$$

where  $E(a)$  is yet another undetermined function. Checking the compatibility conditions  $(l_p)_a = (l_a)_p$ ,  $(n_q)_a = (n_a)_q$  one obtains

$$B = C = \eta', \quad E = \frac{8}{3}\eta'',$$

where  $\eta$  is a solution of the Chazy equation (2). With these formulas the remaining expressions for  $Q_{aaa}$ ,  $Q_{aab}$  and  $Q_{aac}$  hold identically.

Thus, the general solution of the involutive system (14) yields the main classification result of this section:

$$\Omega_{zt} = \frac{1}{4} \ln \frac{\theta_1(\Omega_{xx}, \Omega_{xt} - \Omega_{xz})}{\theta_1(\Omega_{xx}, \Omega_{xt} + \Omega_{xz})},$$

where  $\theta_1$  is the Jacobi theta-function defined by (3).

**Remark:** This formula provides a pseudopotential for the general case

$$\Omega_{tt} = \ln \Omega_{xy} - \ln \theta_1(\Omega_{xt}, \Omega_{xx}) - \frac{1}{4} \int^{\Omega_{xx}} \eta(\tau) d\tau,$$

see the Introduction. All other particular cases can be obtained by appropriate degenerations, see [2].

**Remark:** Under linear transformation of independent variables  $(z, t)$  this equation can be written in more symmetric form

$$e^{\Omega_{zz}} \theta_1(\Omega_{xx}, \Omega_{xz}) = e^{\Omega_{tt}} \theta_1(\Omega_{xx}, \Omega_{xt}).$$

To calculate  $L$  we consider the compatibility condition

$$\partial_z G(a, b, c) = \partial_t Q(e, a, b)$$

which implies

$$G_a e_x + G_b Q(a, b, e)_x + G_c L(e, a, b, c)_x = Q_e Q(a, b, e)_x + Q_a b_x + Q_b G(a, b, c)_x;$$

recall that  $c_z = L(e, a, b, c)_x$ . Therefore,

$$L = Q_b c + f(e, a, b).$$

along with

$$\begin{aligned} Q_{bb} &= \varepsilon(Q_a + Q_b Q_e), & Q_{ab} &= \varepsilon(Q_a Q_e + Q_b F_a - F_b Q_a), \\ Q_{be} &= \varepsilon(Q_e^2 - F_b Q_e - F_a), & f_b &= (\alpha a + \beta b + \gamma)(Q_a + Q_b Q_e), \\ f_a &= (\alpha a + \beta b + \gamma)(Q_a Q_e + Q_b F_a - F_b Q_a) + \frac{1}{\varepsilon}(\alpha Q_b - \beta Q_a), \\ f_e &= (\alpha a + \beta b + \gamma)(Q_e^2 - F_b Q_e - F_a) - \frac{1}{\varepsilon}(\beta Q_e + \alpha). \end{aligned}$$



These relations are sufficient for the reconstruction of  $L$ .

#### 4. Conclusion

We have proved that the method of hydrodynamic reductions applied to quasilinear equations (5) and (13) yields the same classification results as the symmetry approach used in [10]. Thus, both methods allow to classify integrable (2+1)-dimensional equations and find their commuting flows, see [10] for the details.

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